

FIGURE 5.1 Drawings of objects before and after they are transformed.

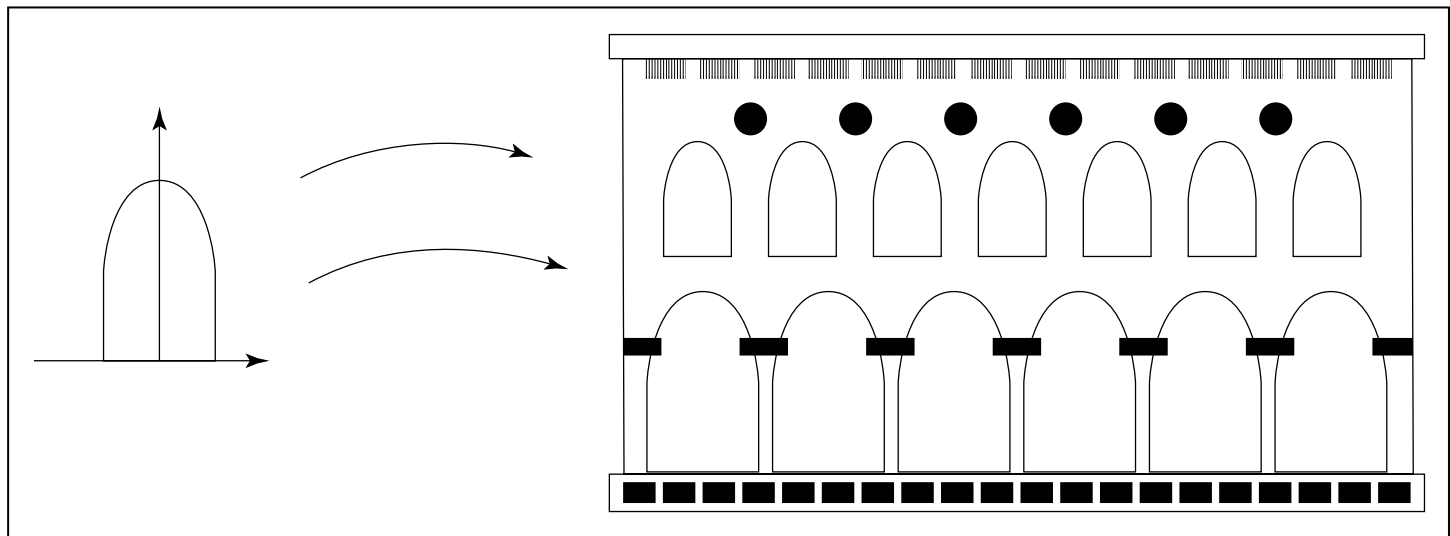
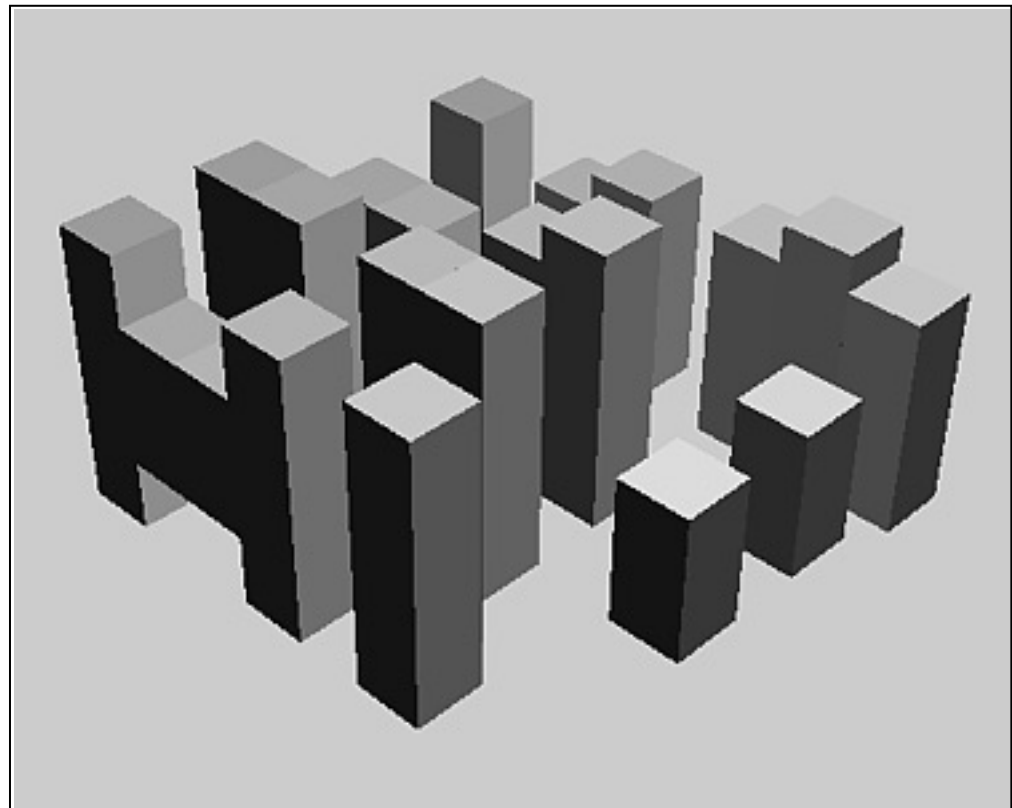


FIGURE 5.2 Composing a picture from many instances of a simple form.

FIGURE 5.3 Composing a 3D scene from primitives.



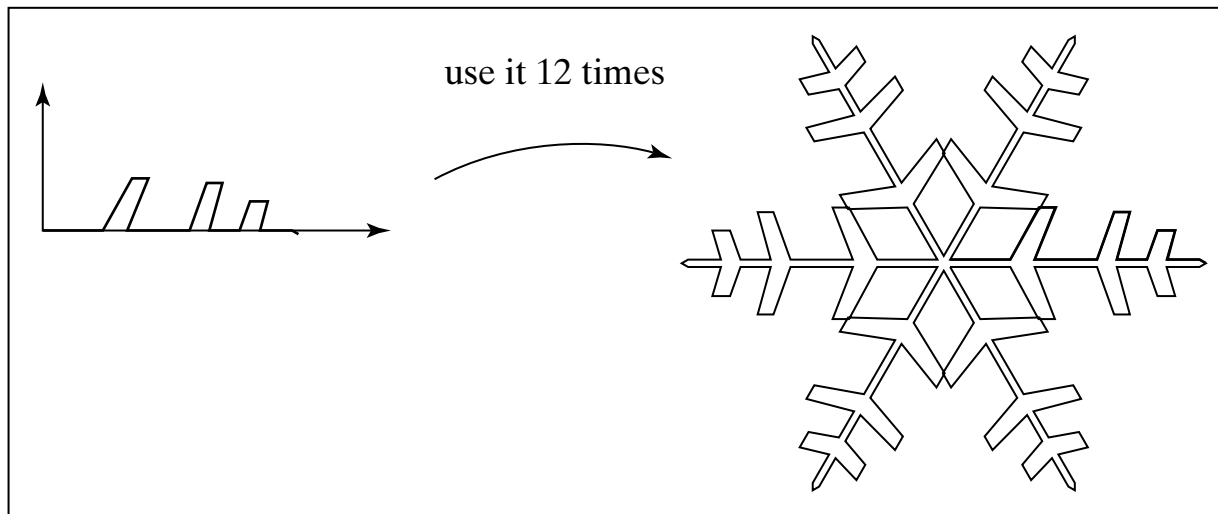
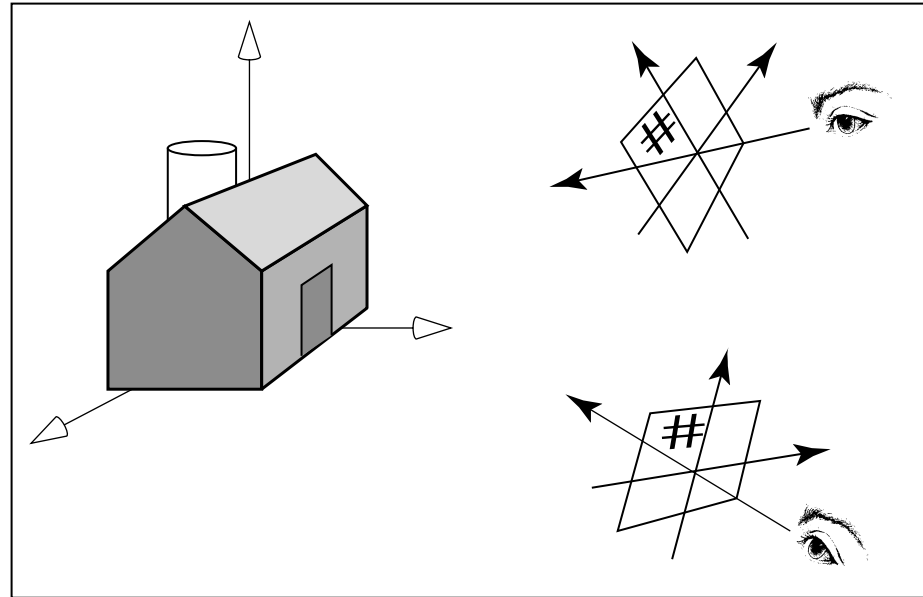


FIGURE 5.4 Using a “motif” to build up a figure.

FIGURE 5.5 Viewing a scene from different vantage points.



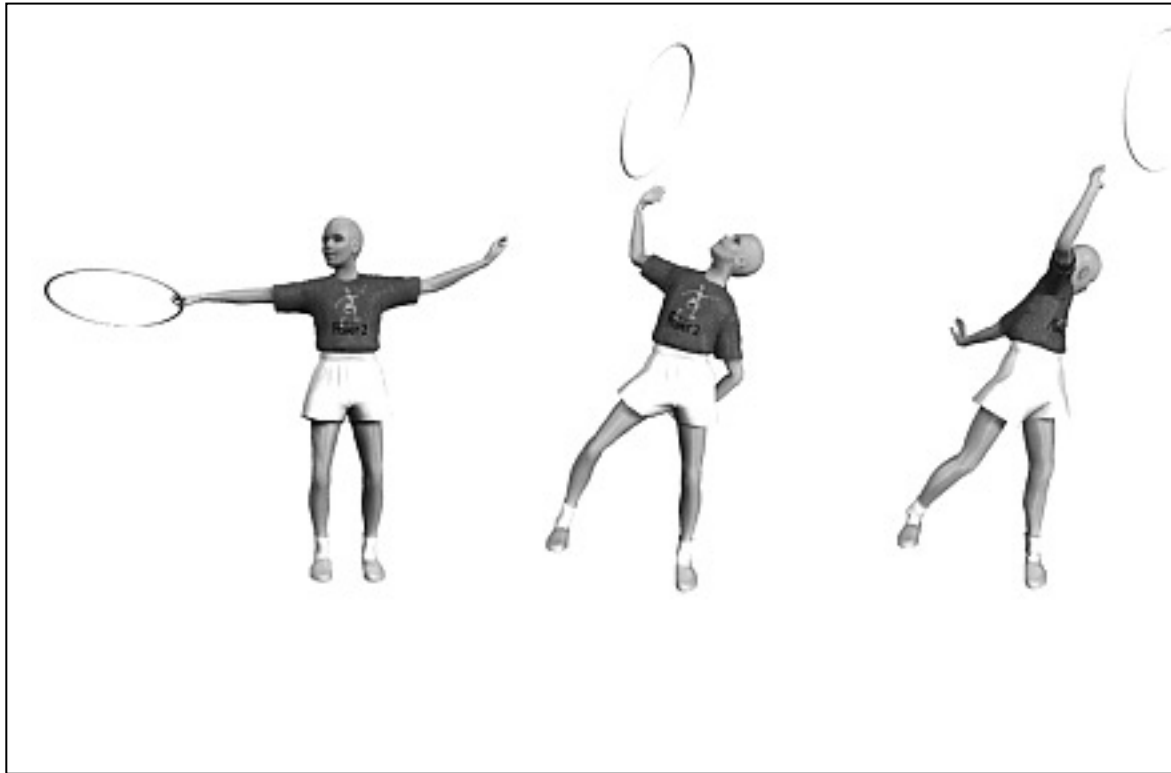


FIGURE 5.6 Animating by transforming shapes.

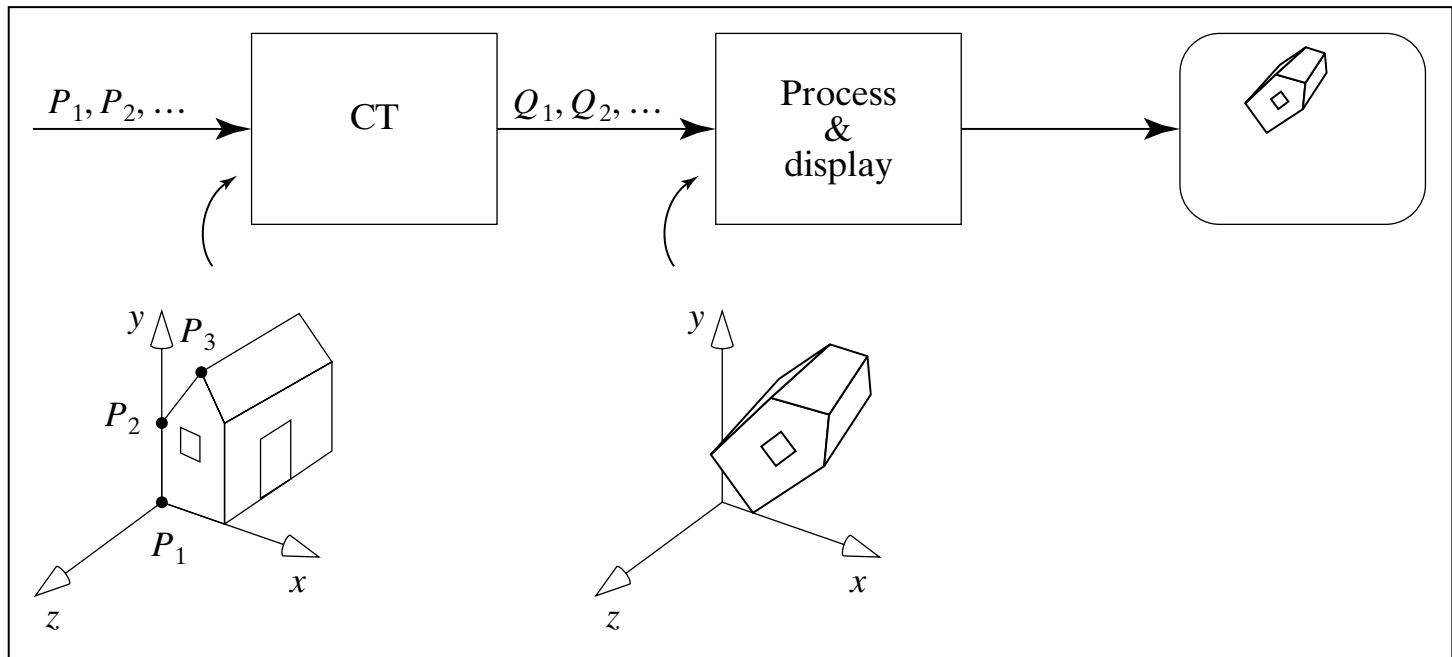
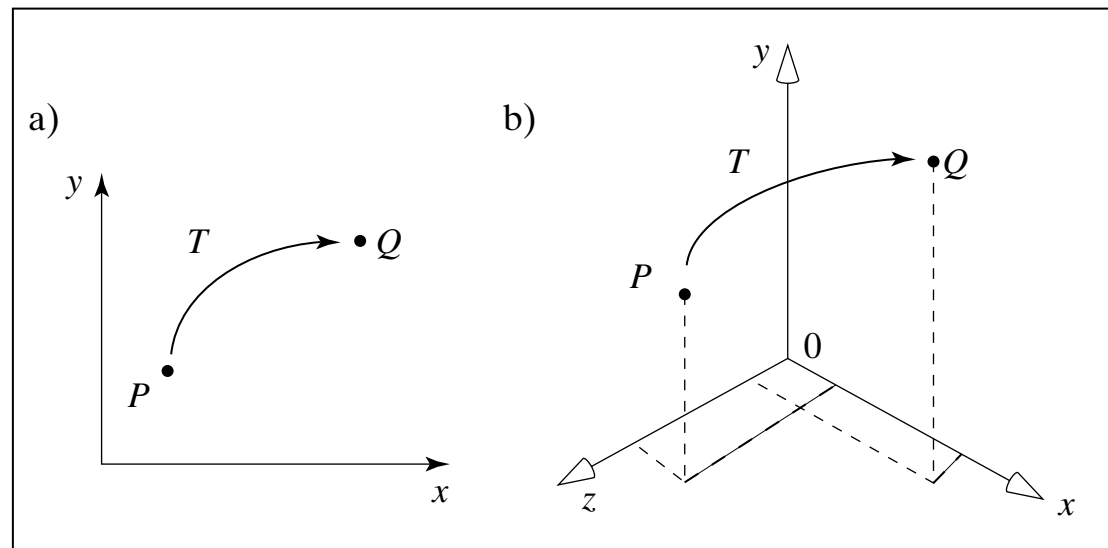


FIGURE 5.7 The OpenGL pipeline.

FIGURE 5.8 Mapping points into new points.



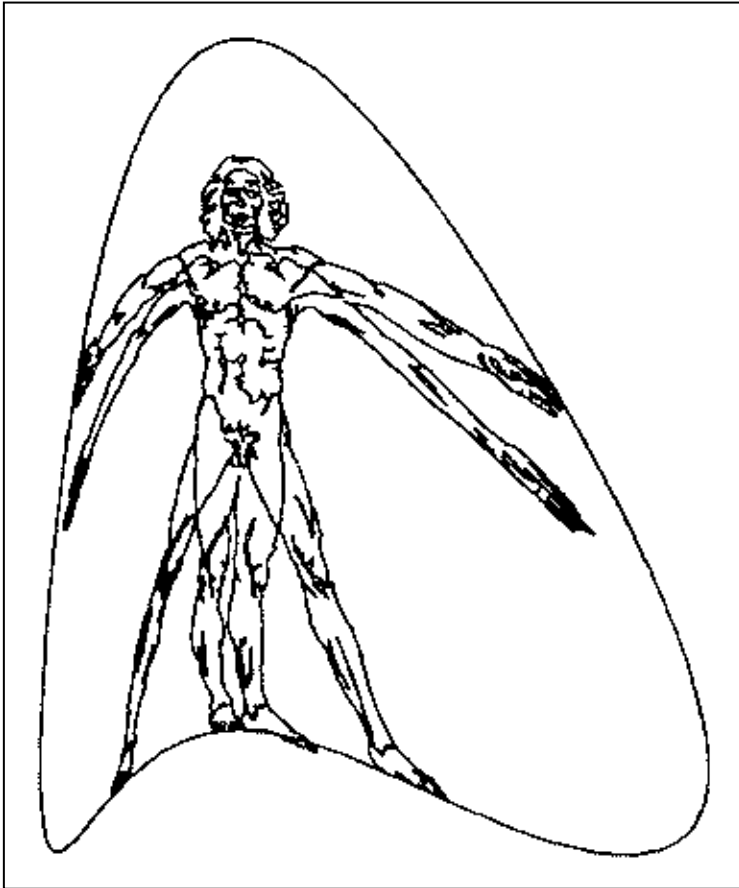
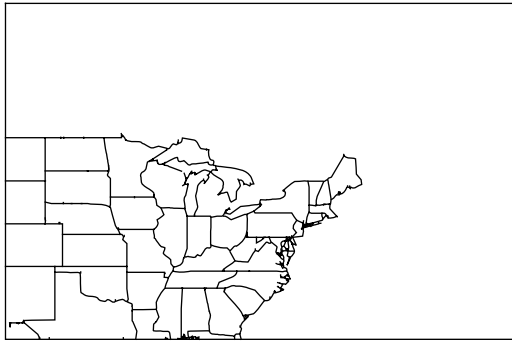
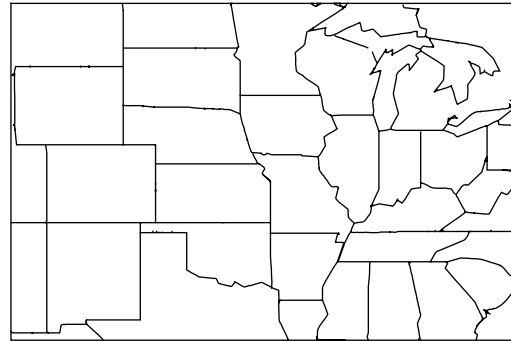


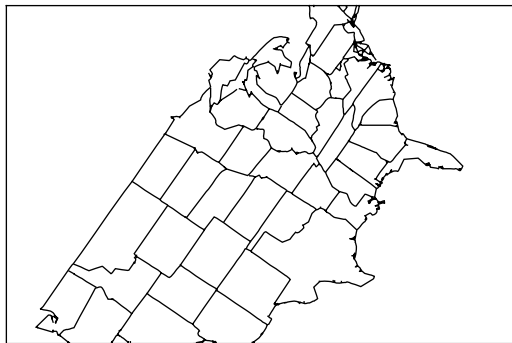
FIGURE 5.9 A complex warping of a figure.



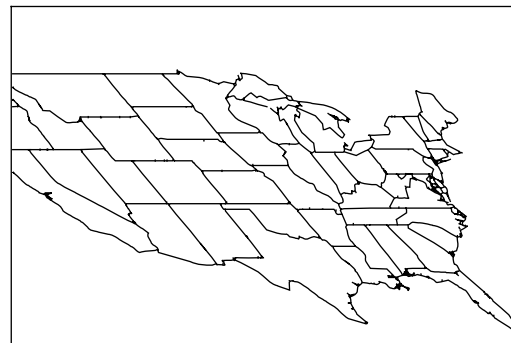
a)



b)



c)



d)

FIGURE 5.10 Transformations of a map: (a) translation; (b) scaling; (c) rotation; (d) shear.

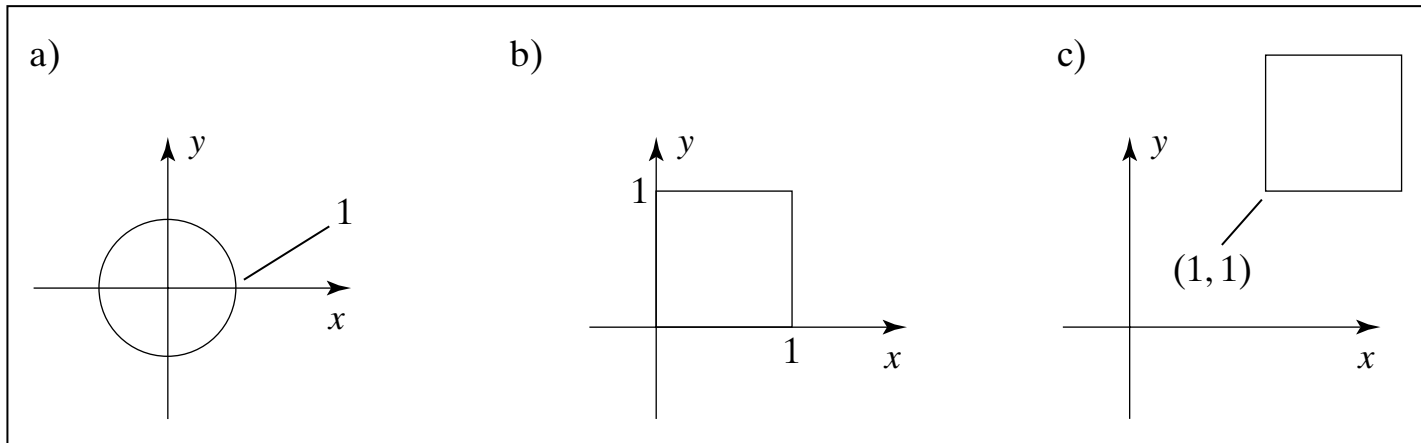


FIGURE 5.12 Objects to be scaled.

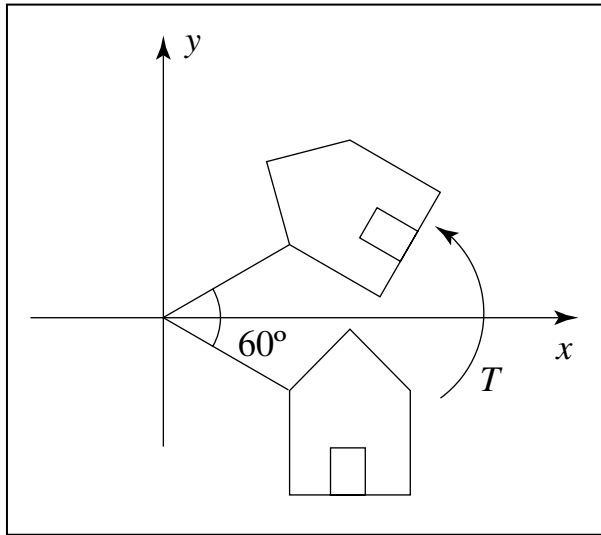


FIGURE 5.13 Rotation of points through an angle of 60° .

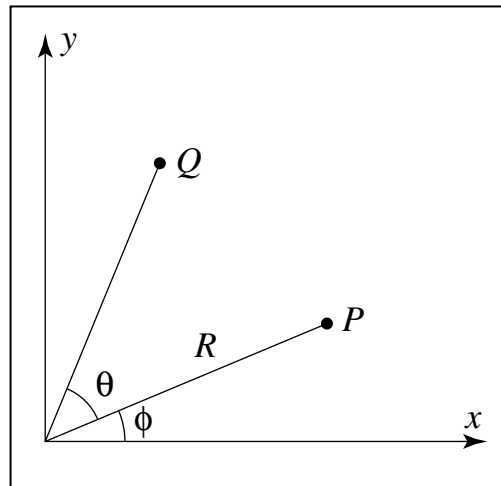


FIGURE 5.14 Derivation of the rotation mapping.

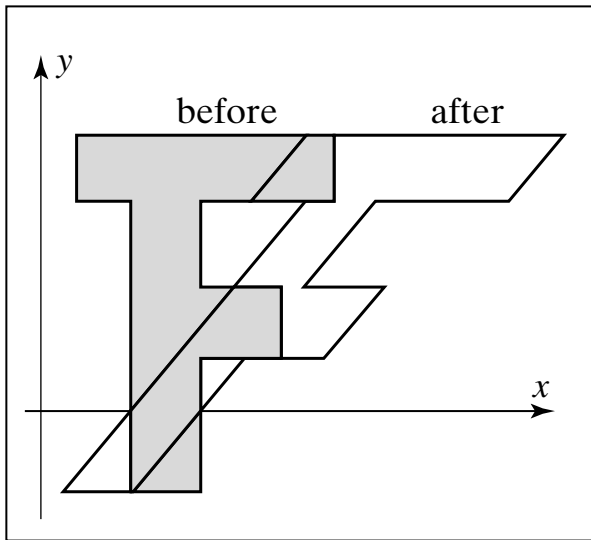


FIGURE 5.15 An example of shearing.

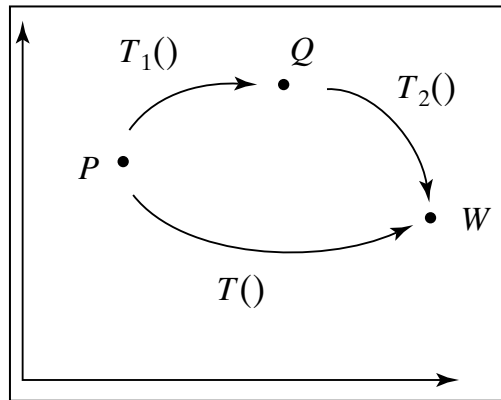


FIGURE 5.16 The composition of two transformations.

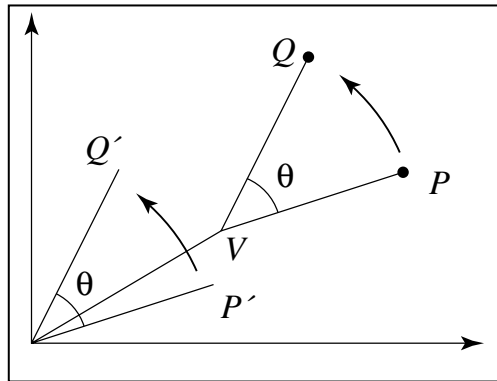


FIGURE 5.17 Rotation about a point.

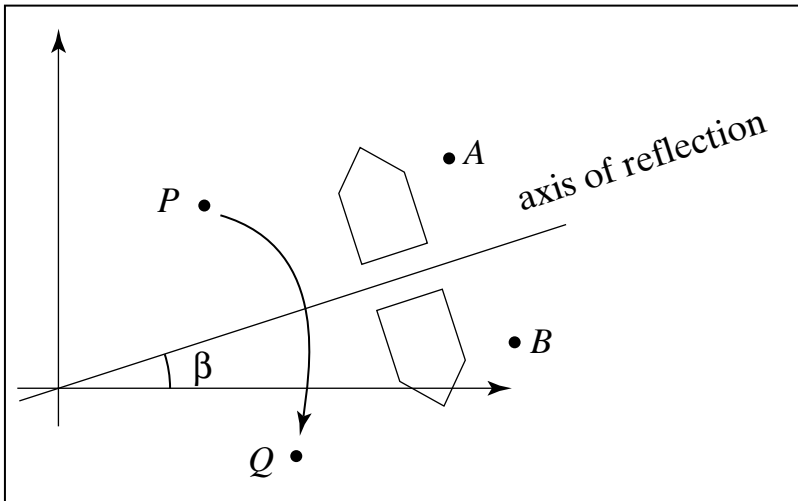


FIGURE 5.18 Reflecting a point about a tilted axis.

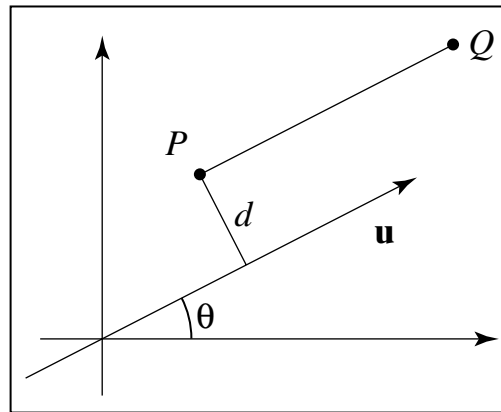


FIGURE 5.19 Shearing along a tilted axis.

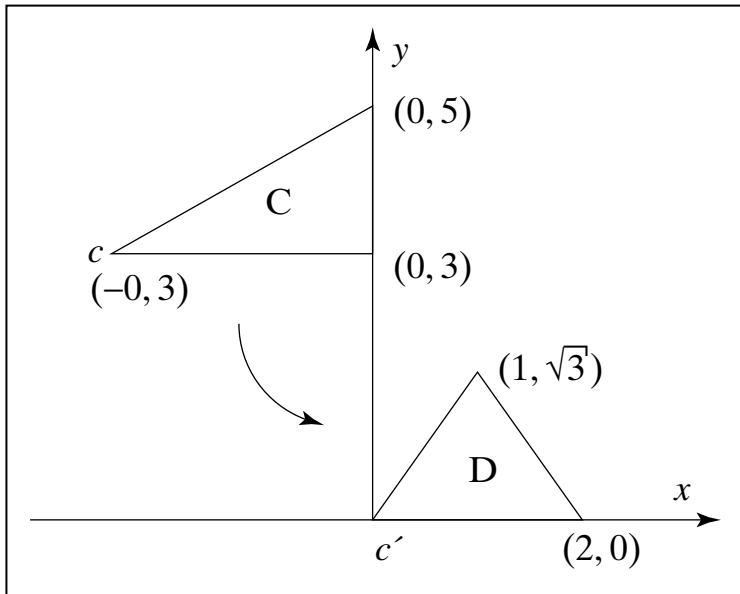
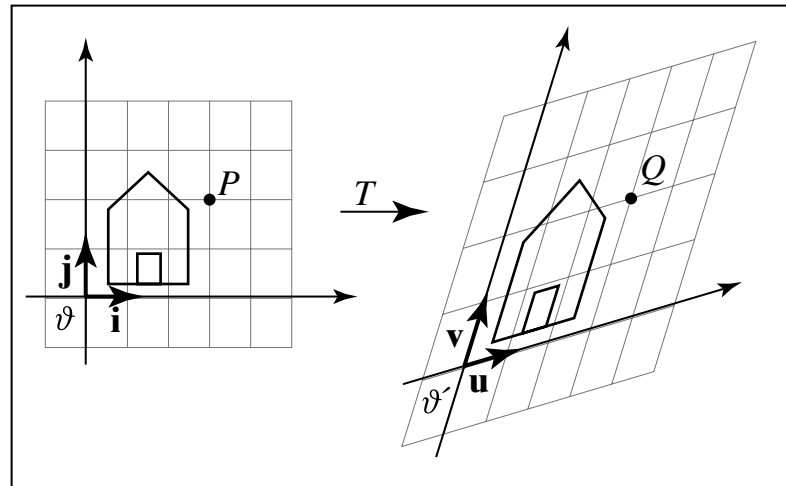


FIGURE 5.20 Converting one triangle into another.

FIGURE 5.21 A transformed grid.



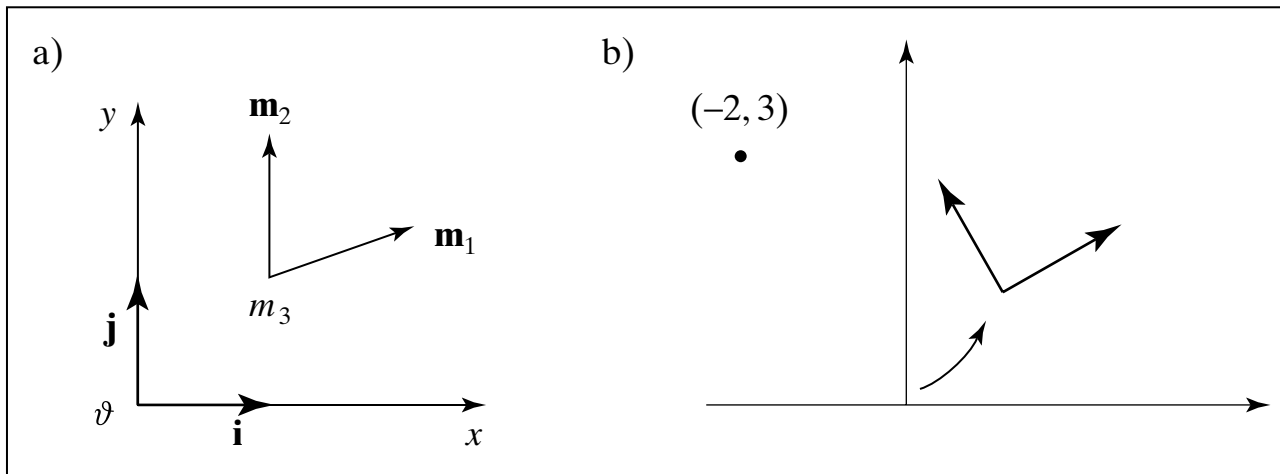


FIGURE 5.22 The transformation forms a new coordinate frame.

FIGURE 5.23 Relative ratios are preserved.

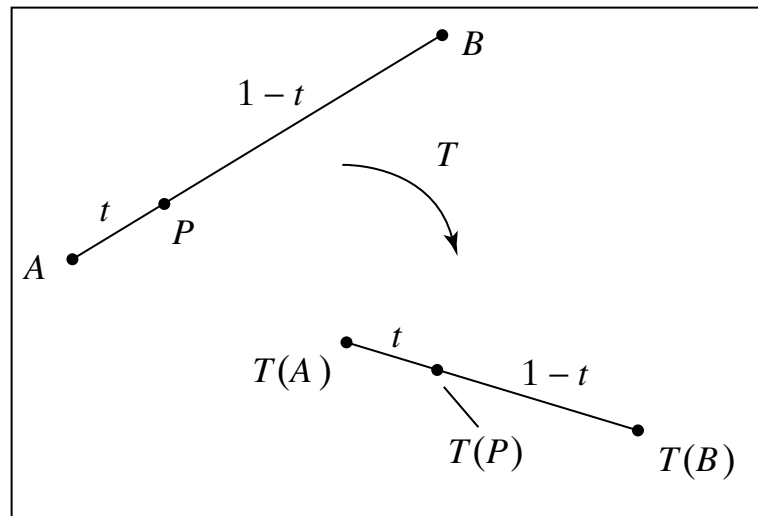
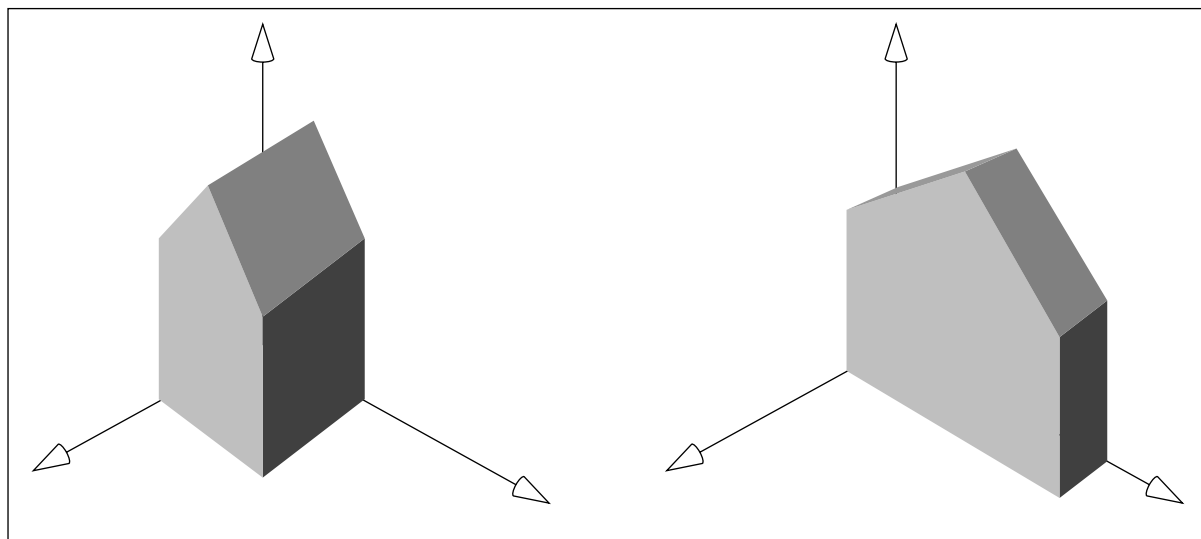


FIGURE 5.24 Scaling the basic
cuboid.



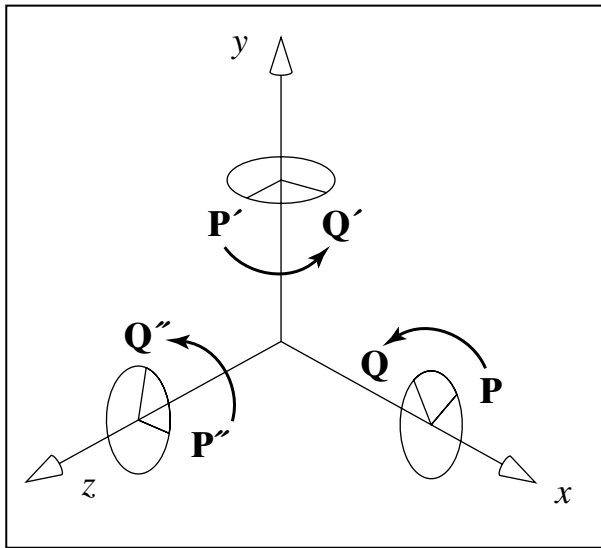


FIGURE 5.25 Positive rotations about the three axes.

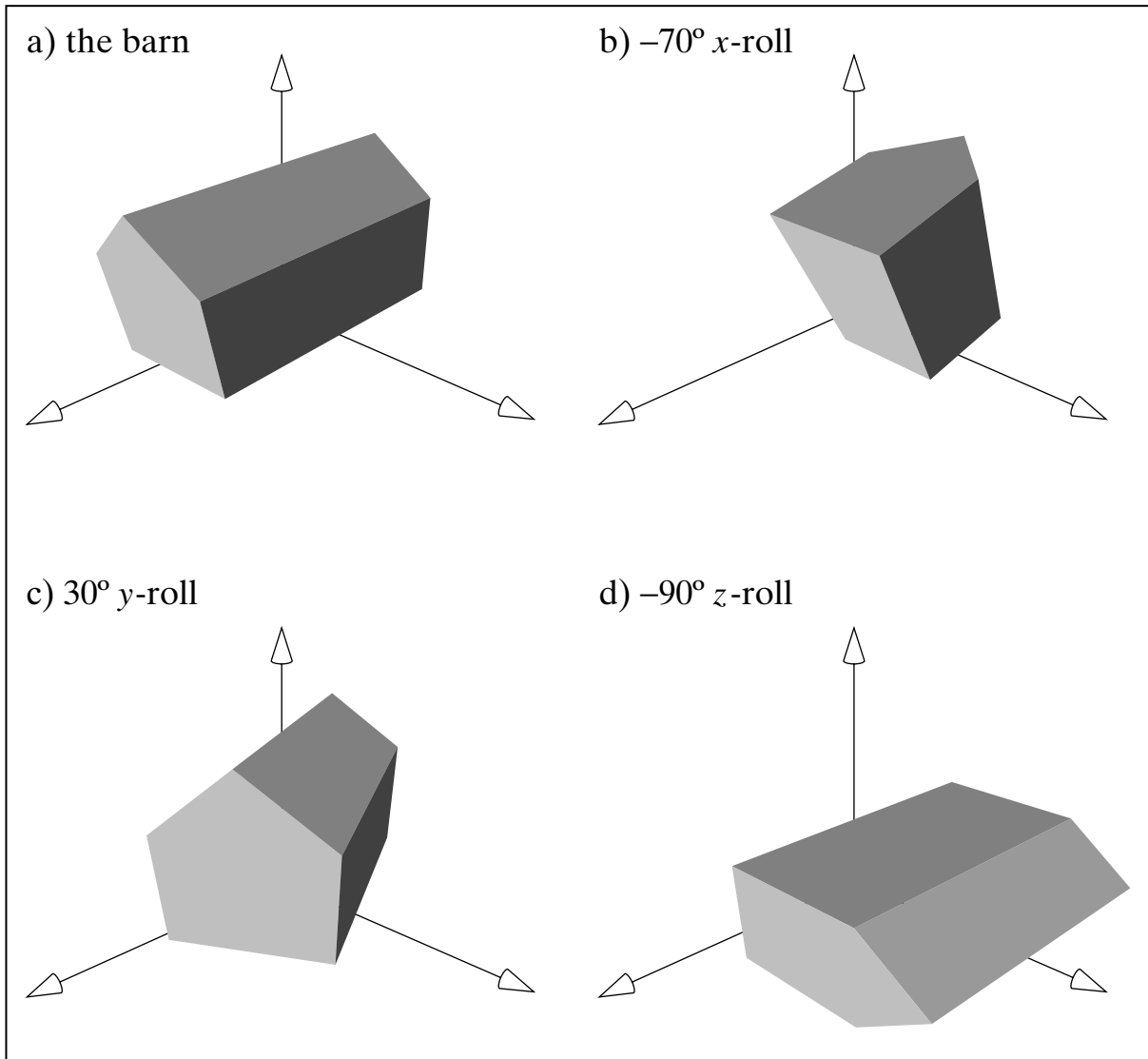


FIGURE 5.26 Rotating the basic barn.

FIGURE 5.27 Composing 3D affine transformations.

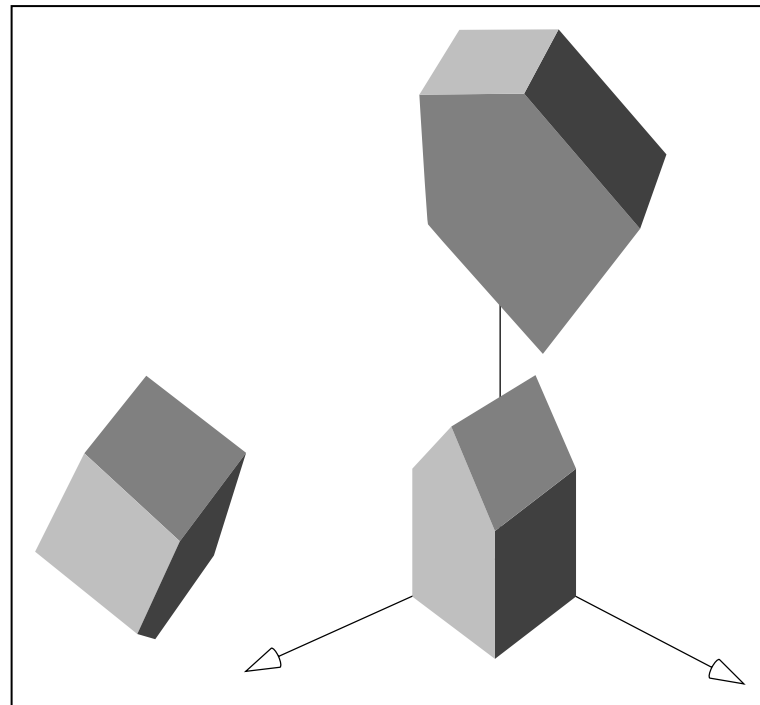
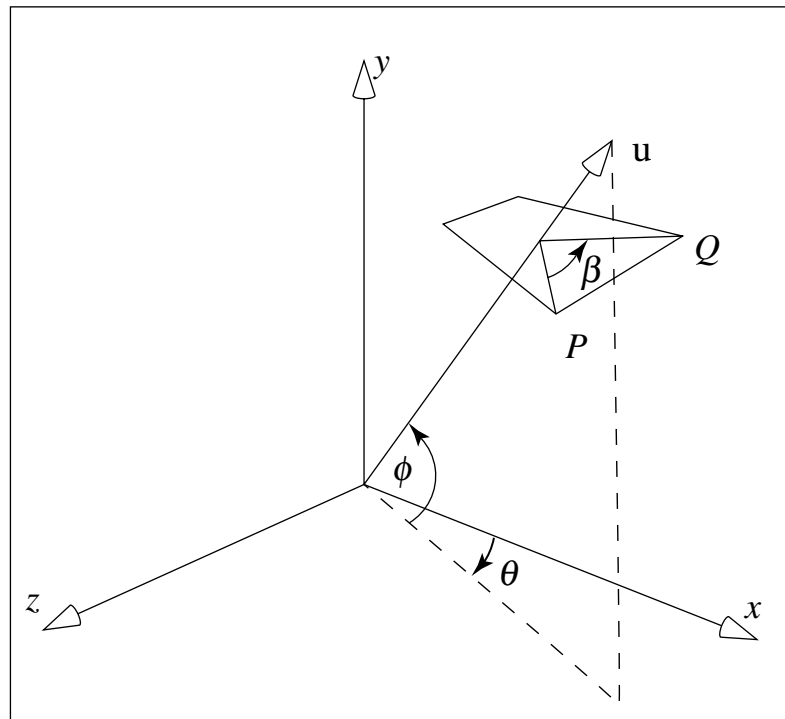


FIGURE 5.28 Rotation about an axis through the origin.



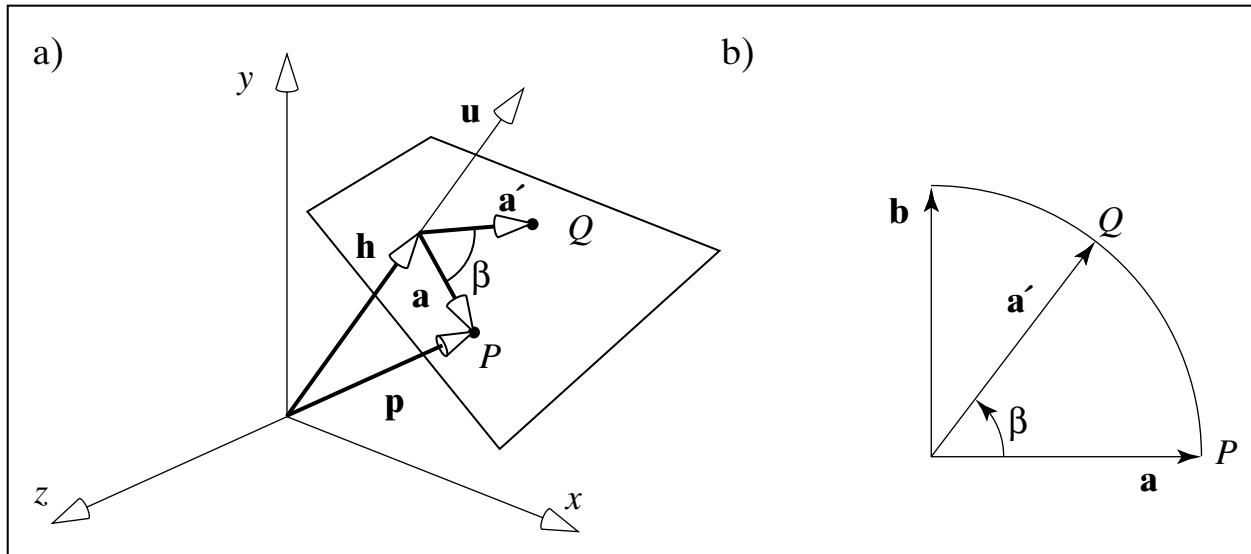


FIGURE 5.29 P rotates to Q in the plane of rotation.

FIGURE 5.30 The basic barn rotated about axis **u**.

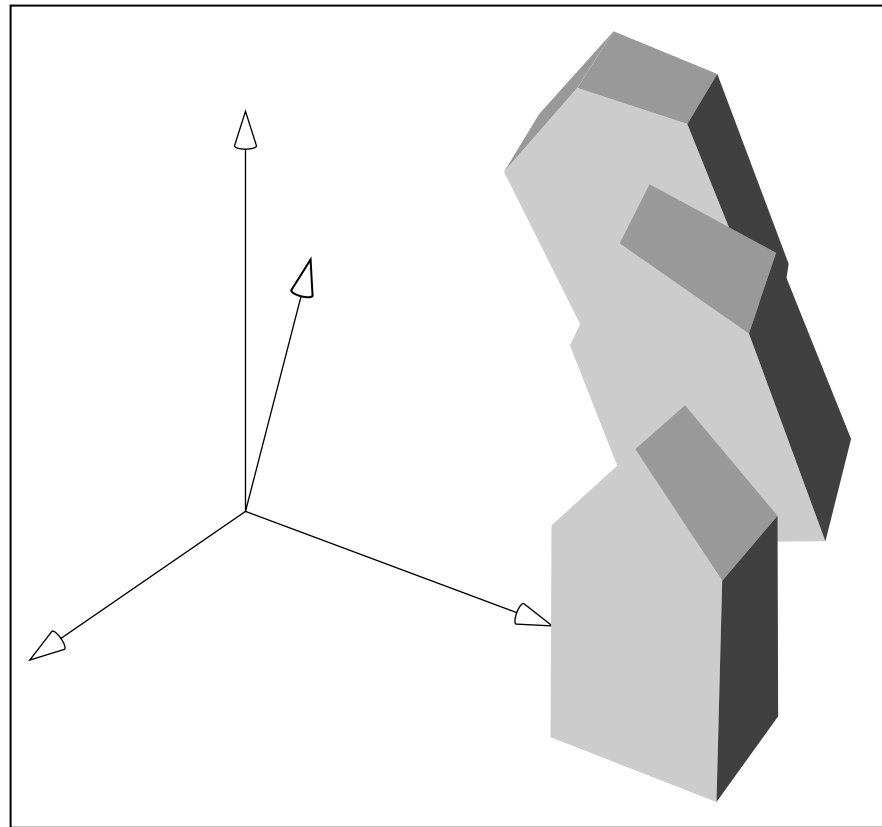
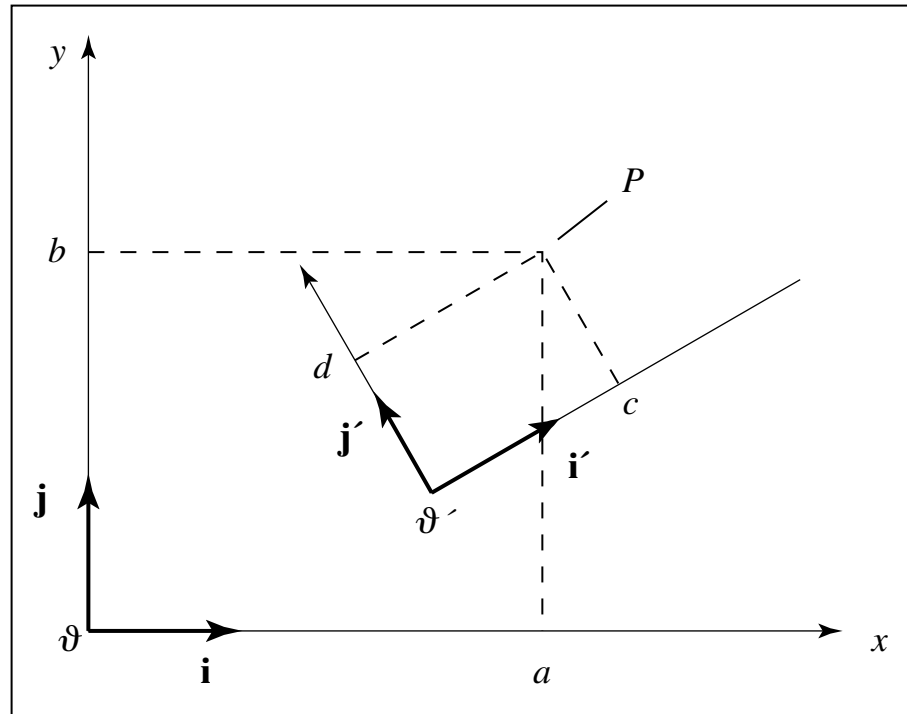


FIGURE 5.31 Transforming a coordinate frame.



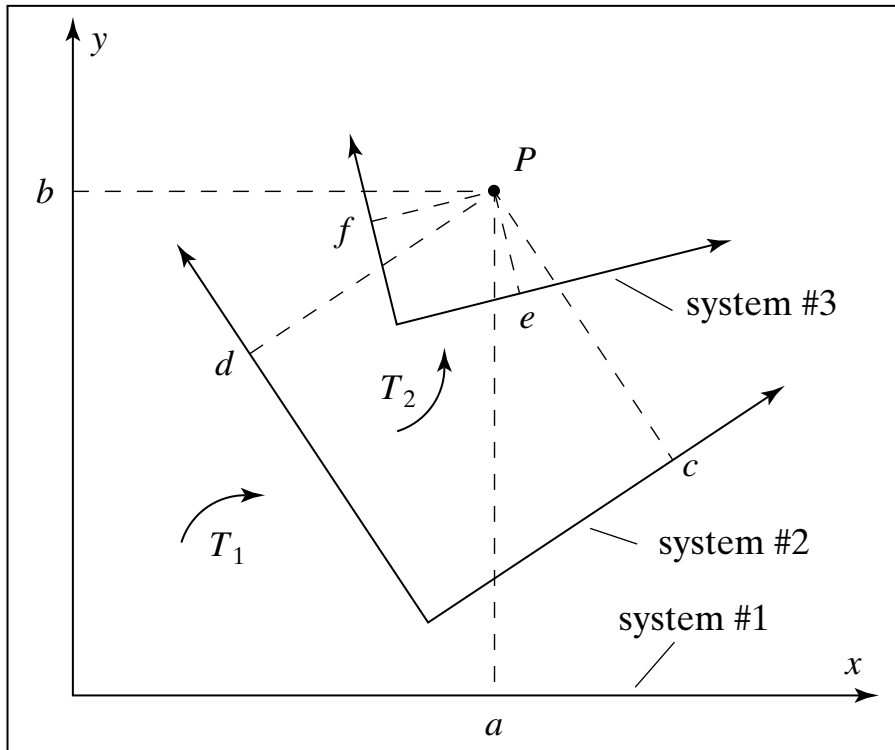


FIGURE 5.32 Transforming a coordinate system twice.

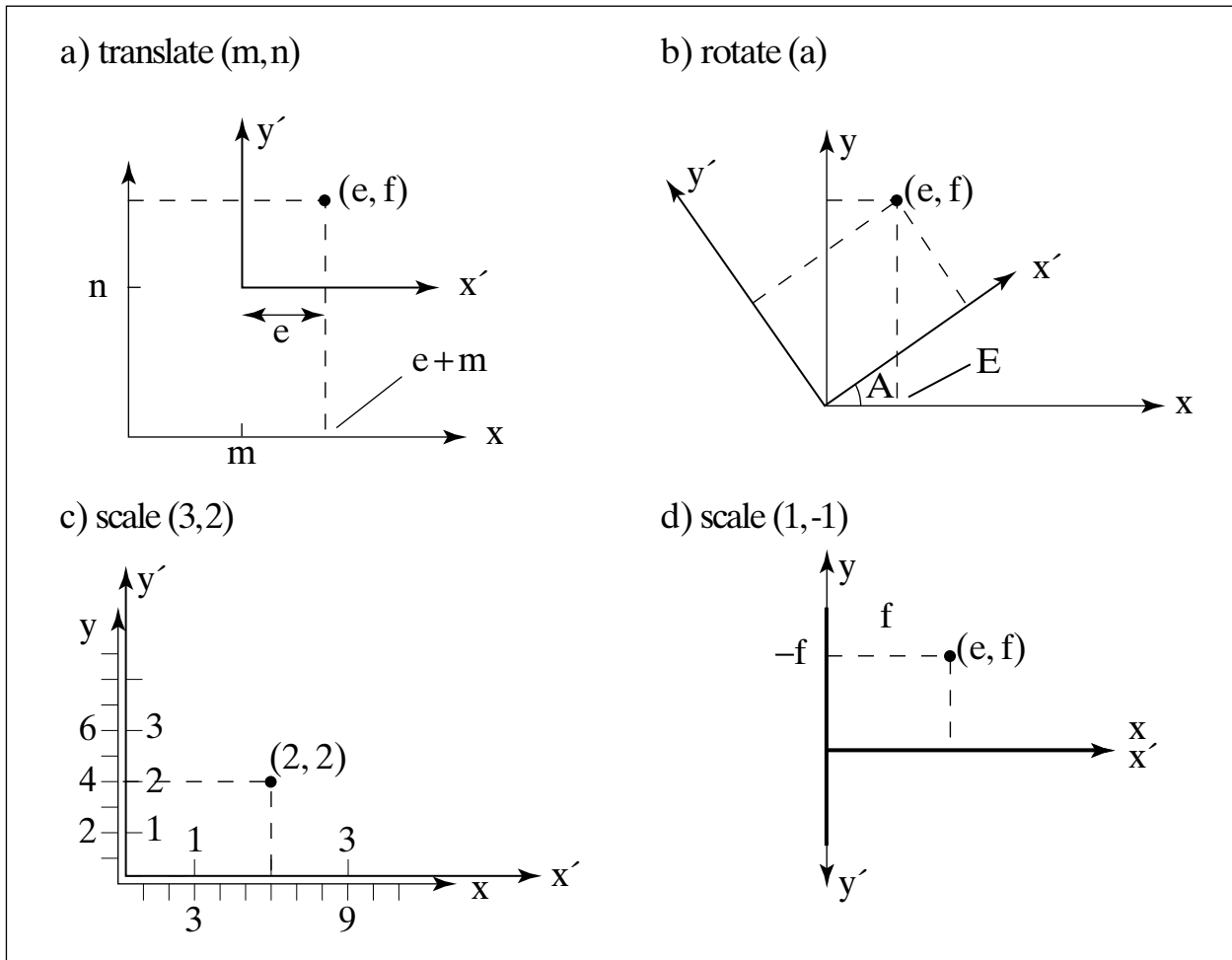
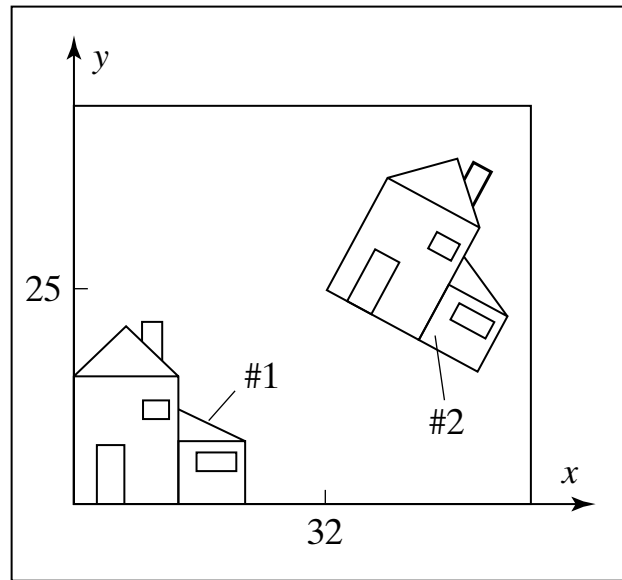


FIGURE 5.33 Elementary changes between coordinate systems.

FIGURE 5.34 Drawing a rotated and translated house.



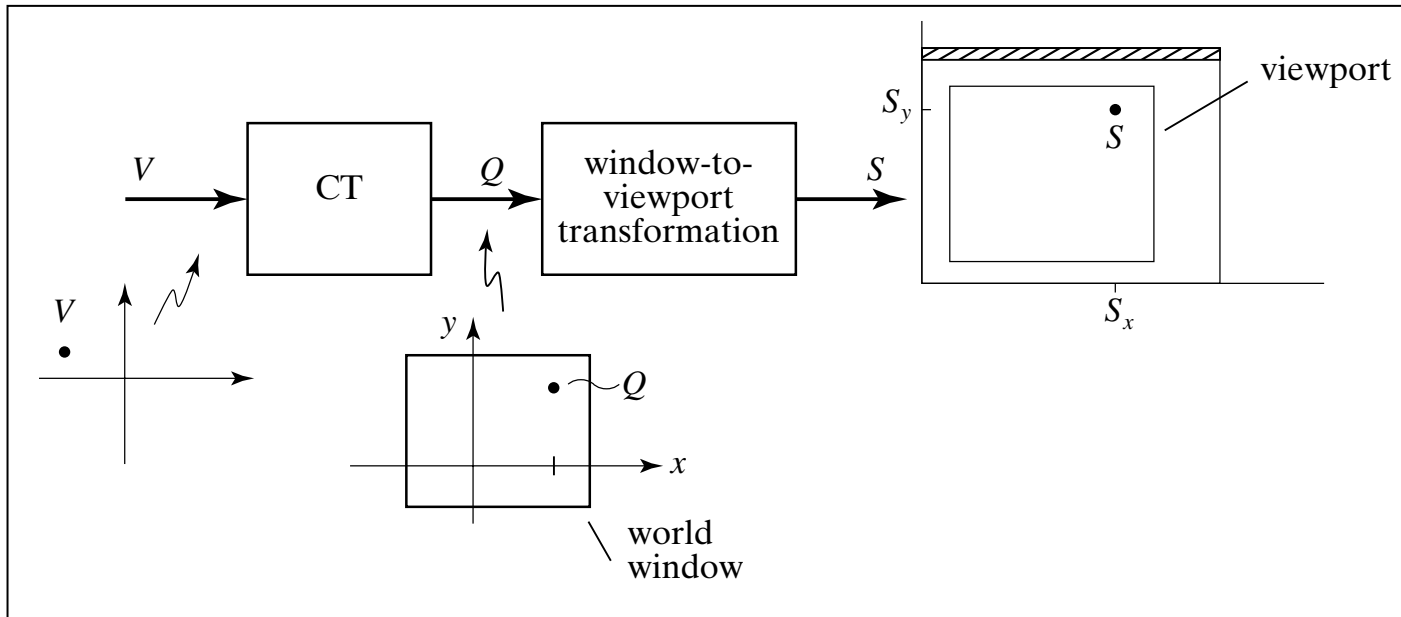


FIGURE 5.35 The current transformation is applied to vertices.

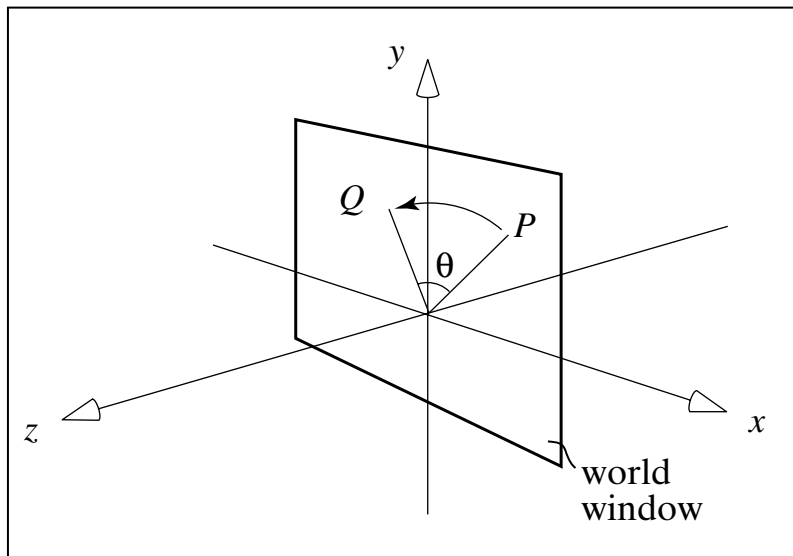


FIGURE 5.36 2D drawing takes place in the xy -plane.

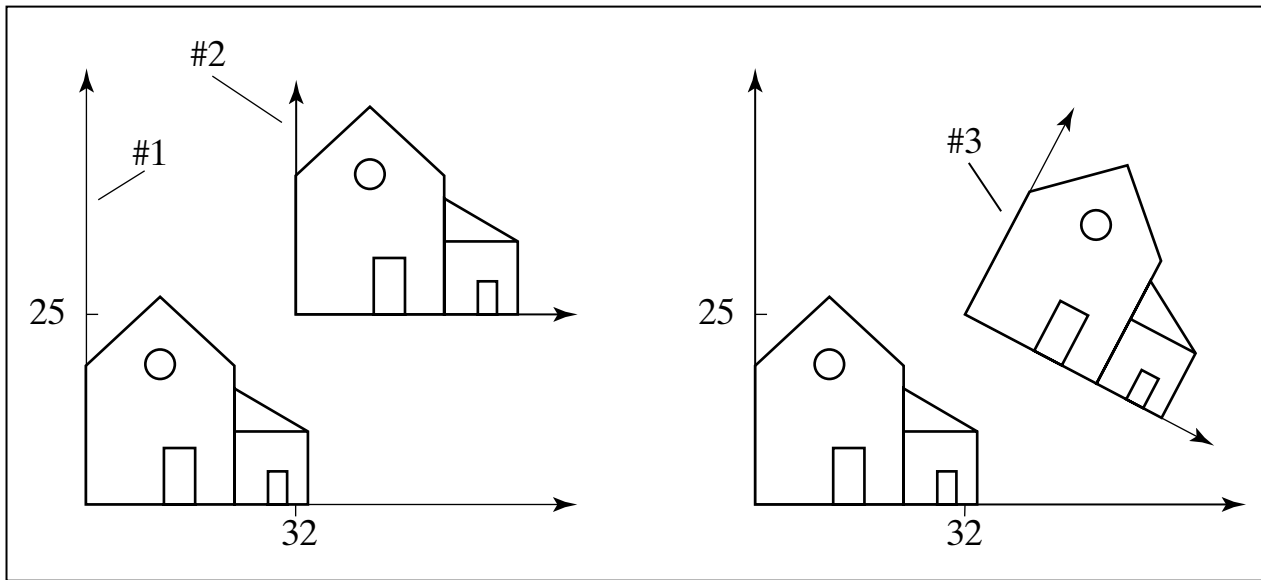


FIGURE 5.38 The same transformation viewed as a sequence of changes of coordinate systems.

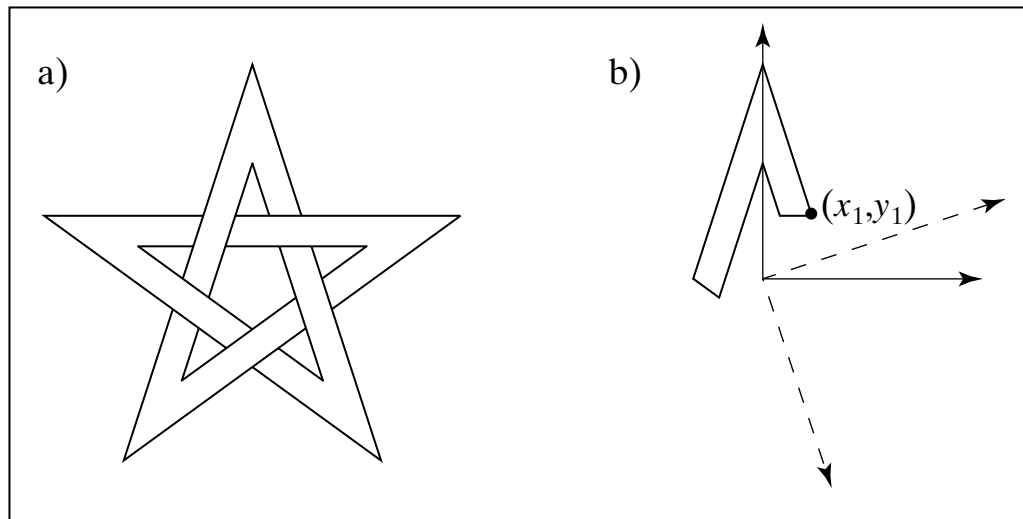
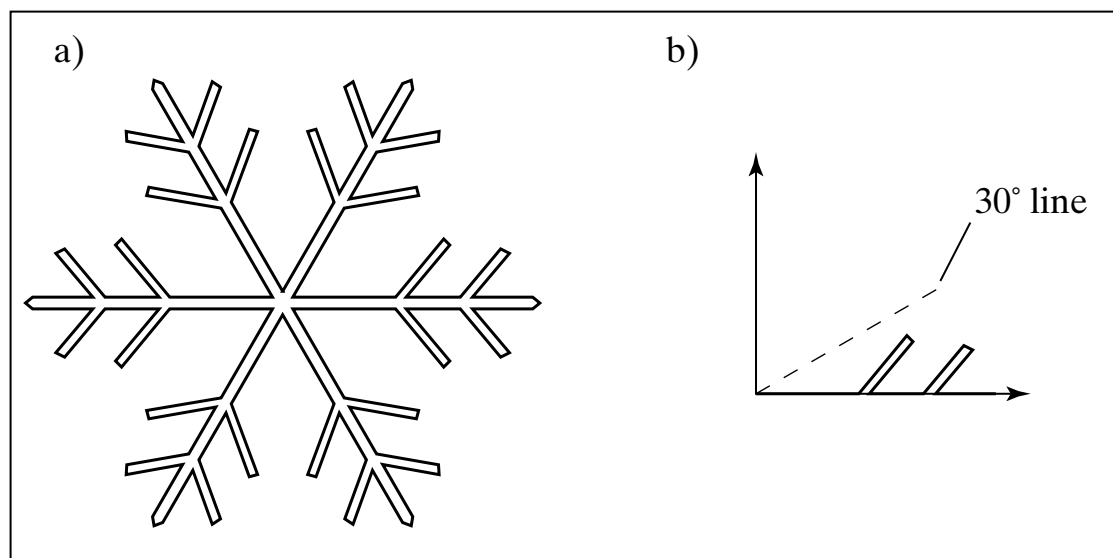


FIGURE 5.39 Using successive rotations of the coordinate system.

FIGURE 5.40 Designing a snowflake.



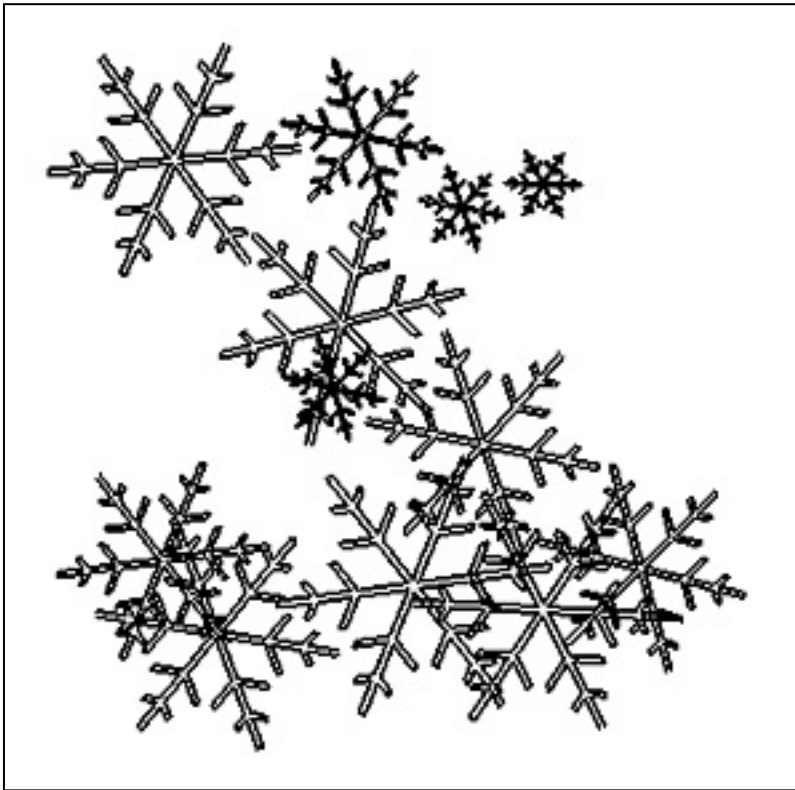
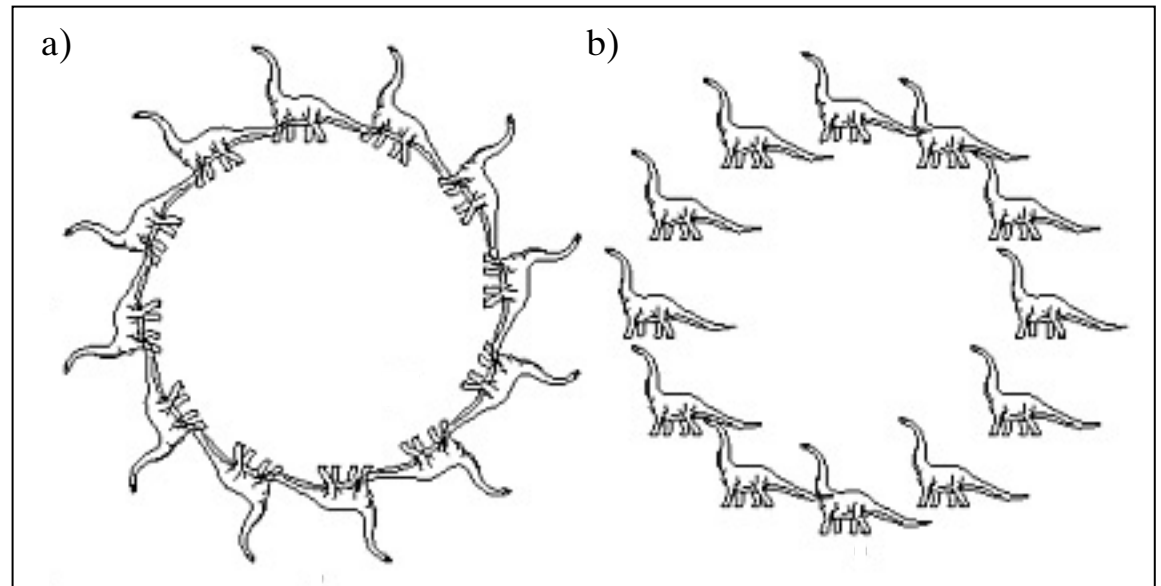


FIGURE 5.41 A flurry of snowflakes.

FIGURE 5.42 Two patterns based on a motif. (a) Each motif is rotated separately. (b) All motifs are upright.



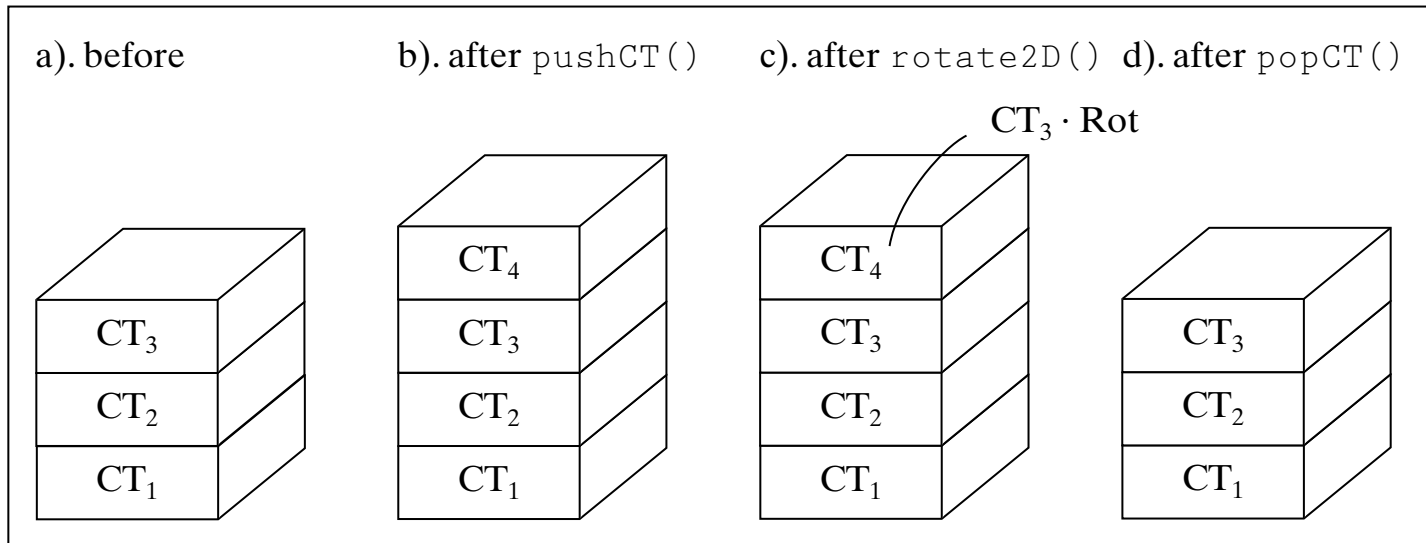


FIGURE 5.43 Manipulating a stack of CT's.

FIGURE 5.44 Routines to save and restore CT's.

```
void Canvas:: pushCT(void)
{
    glMatrixMode(GL_MODELVIEW);
    glPushMatrix();           // push a copy of the top matrix
}
void Canvas:: popCT(void)
{
    glMatrixMode(GL_MODELVIEW);
    glPopMatrix();           // pop the top matrix from the stack
}
```

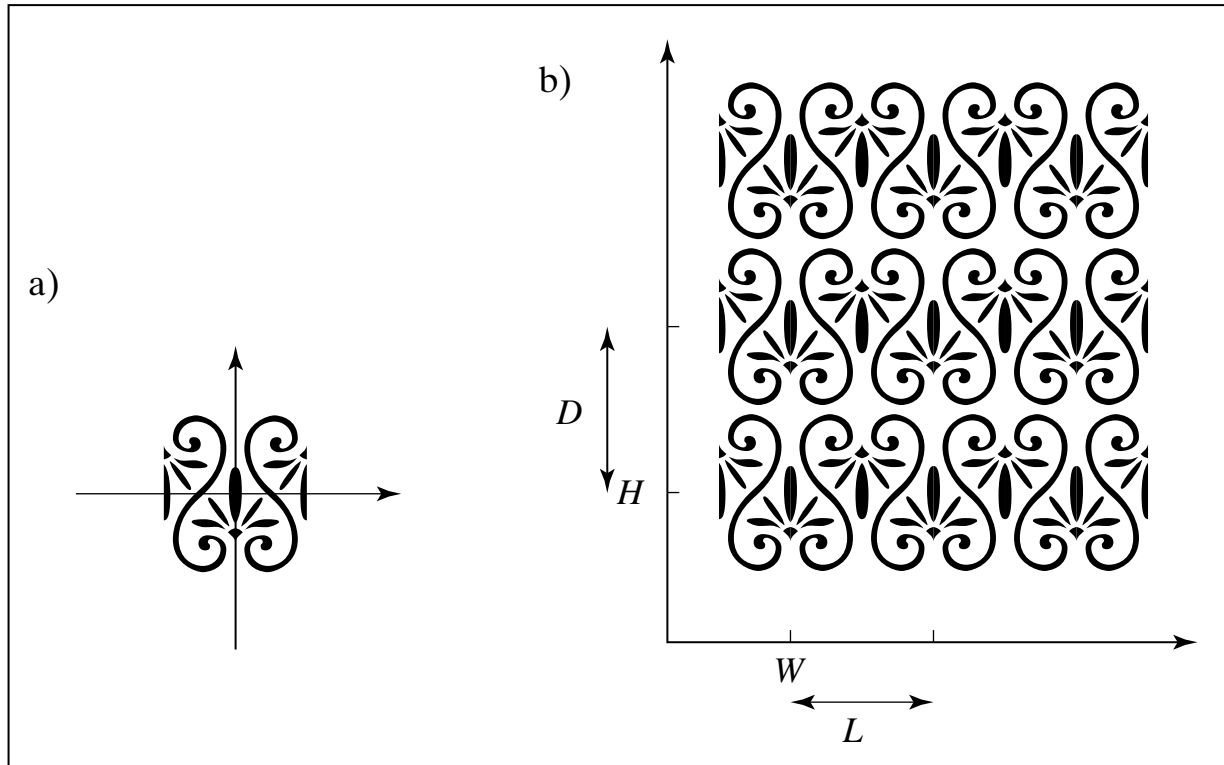


FIGURE 5.45 A tiling based on a motif. (a) The motif. (b) The tiling.

```
cvx.pushCT();    // so we can return here
cvx.translate2D(W, H);    // position for the first motif
for(row = 0; row < 3; row++) // draw each row
{
    cvx.pushCT();
    for(col = 0; col < 4; col++) // draw the next row of motifs
    {
        motif();
        cvx.translate2D(L, 0); // move to the right
    }
    cvx.popCT();    // back to the start of this row
    cvx.translate2D(0, D); // move up to the next row
}
cvx.popCT();    // back to where we started
```

FIGURE 5.46 Drawing a hexagonal tiling.

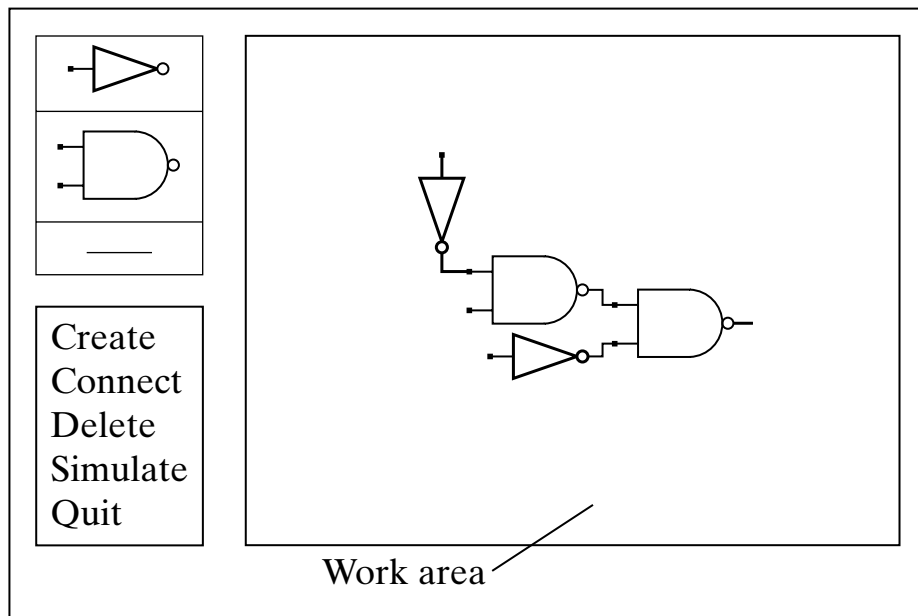


FIGURE 5.47 Creating instances in a pick-and-place application.

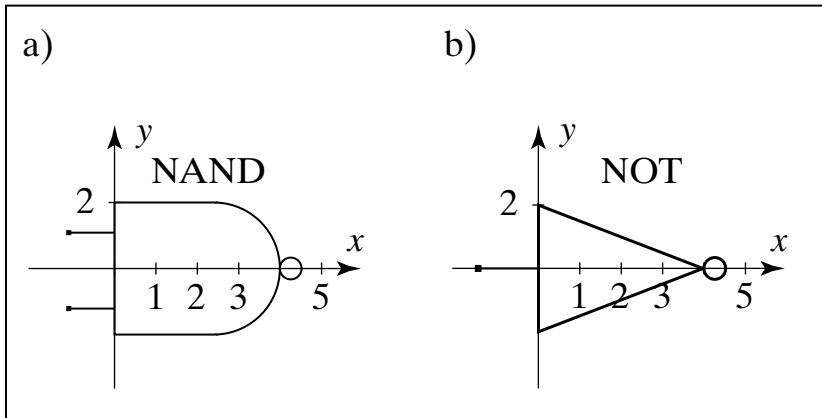
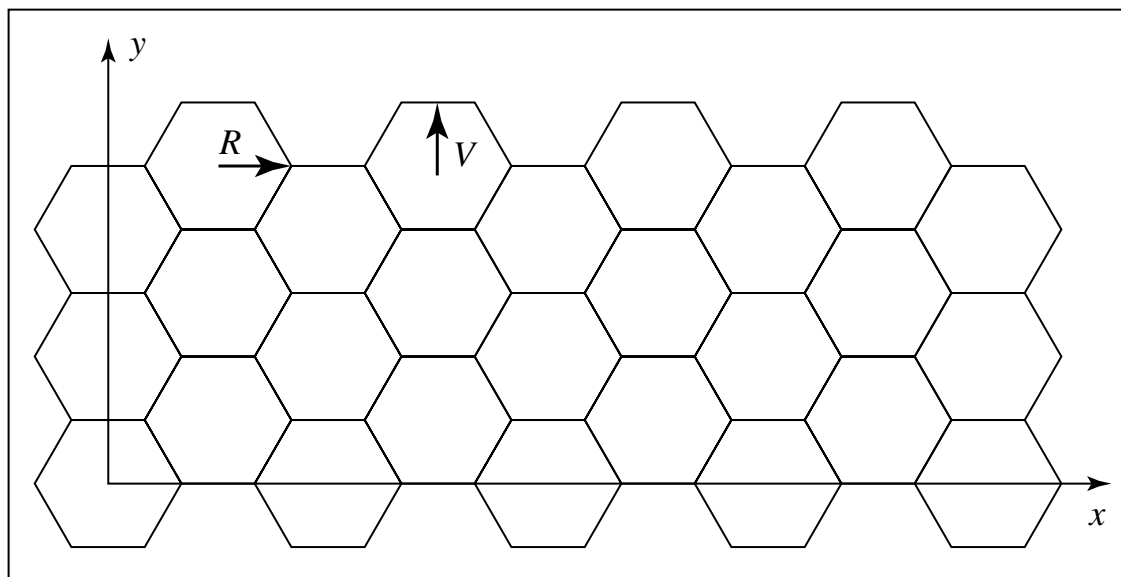


FIGURE 5.48 Each type of gate is defined in its own coordinate system.

FIGURE 5.49 A simple hexagonal tiling.



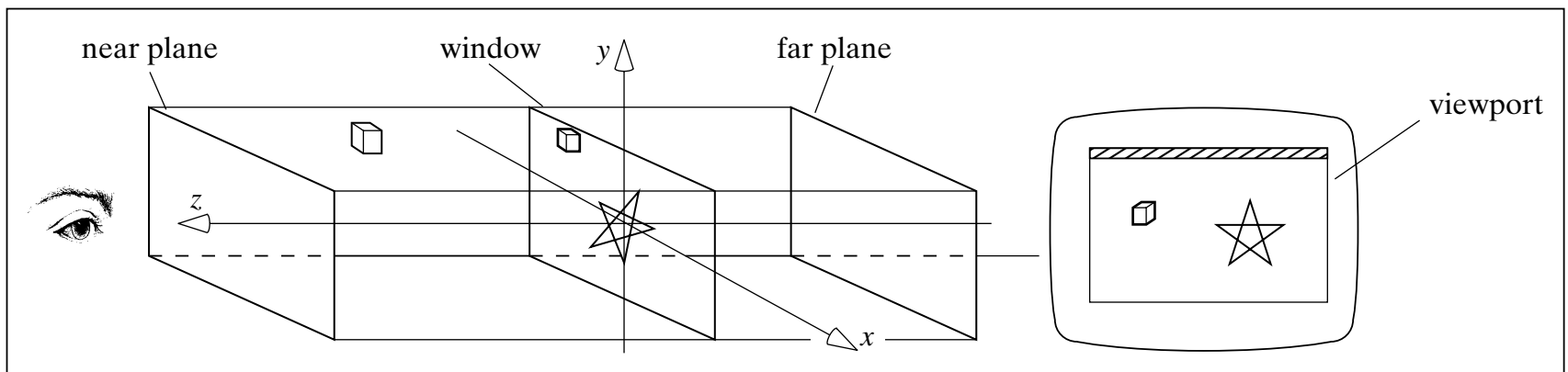


FIGURE 5.50 Simple viewing used in OpenGL for 2D drawing.

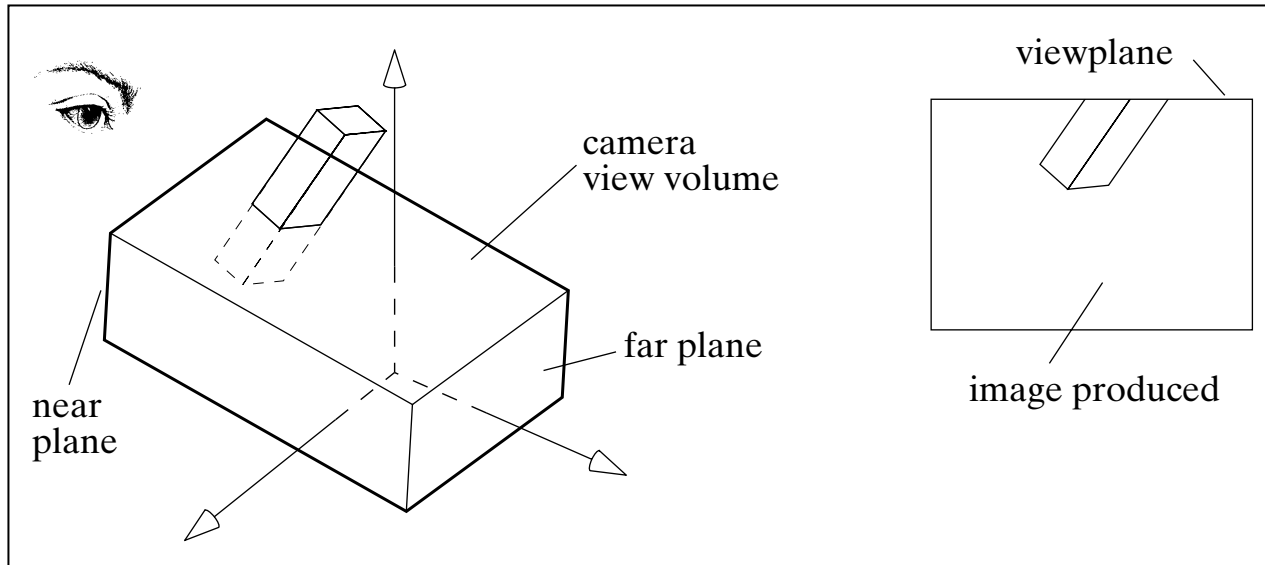
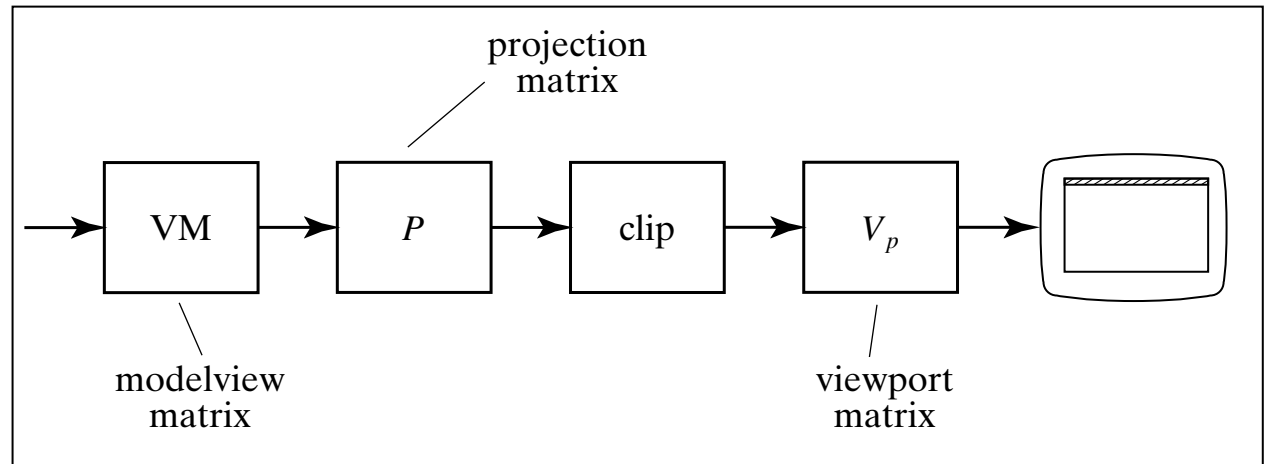


FIGURE 5.51 A camera to produce parallel views of a scene.

FIGURE 5.52 The OpenGL pipeline (slightly simplified).



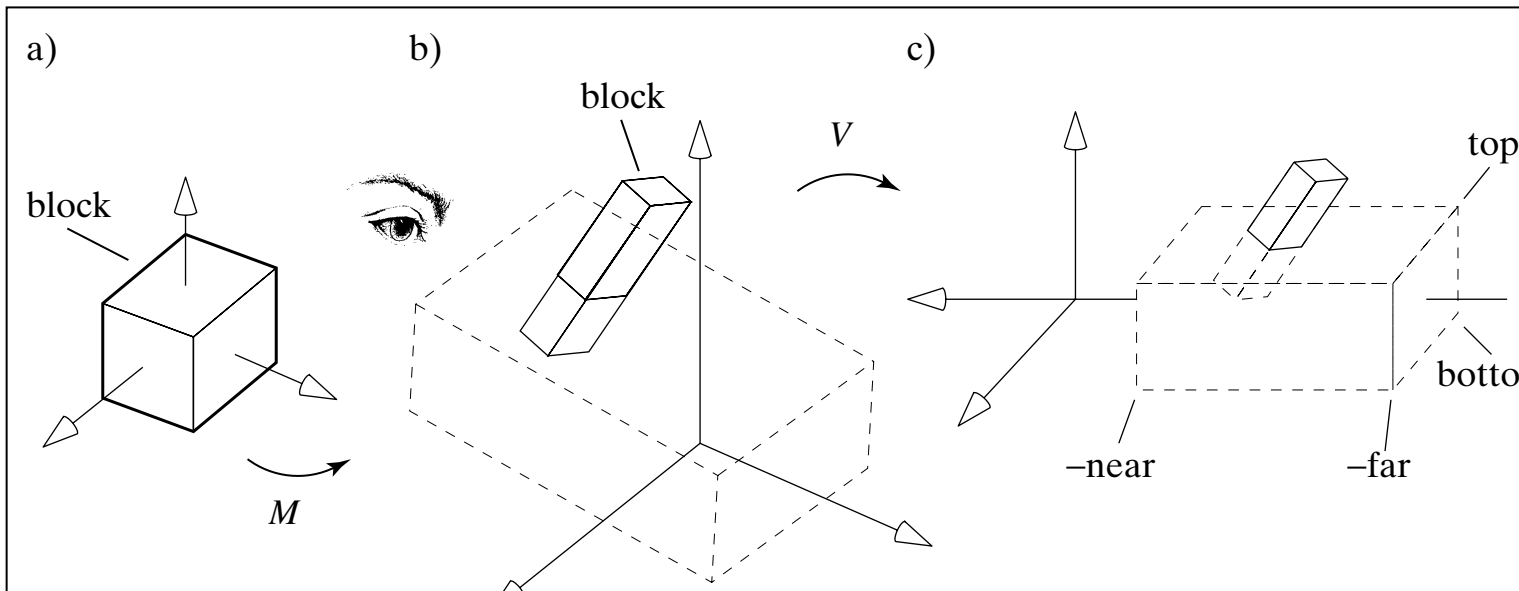


FIGURE 5.53 Effect of the modelview matrix in the graphics pipeline. (a) Before the transformations. (b) After the modeling transformation. (c) After the modelview transformation.

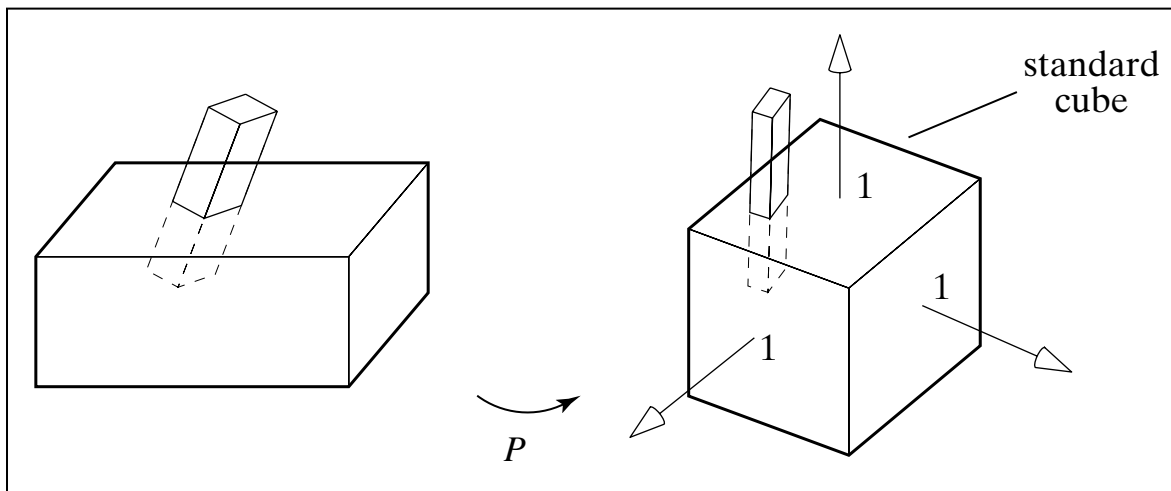


FIGURE 5.54 Effect of the projection matrix (for parallel projections).

FIGURE 5.55 Effect of the viewport transformation.

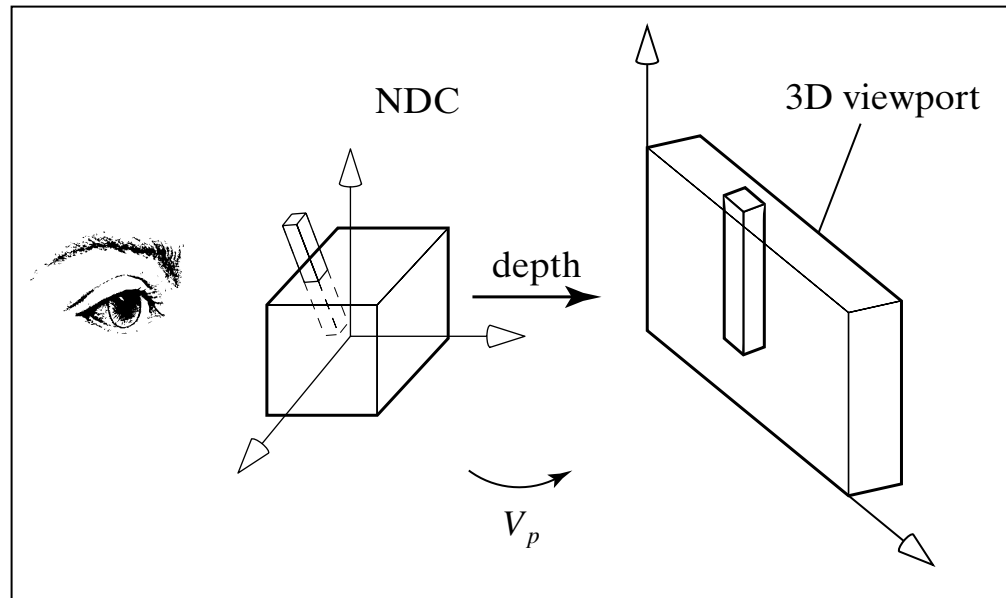


FIGURE 5.56 Setting a camera with `gluLookAt()`.

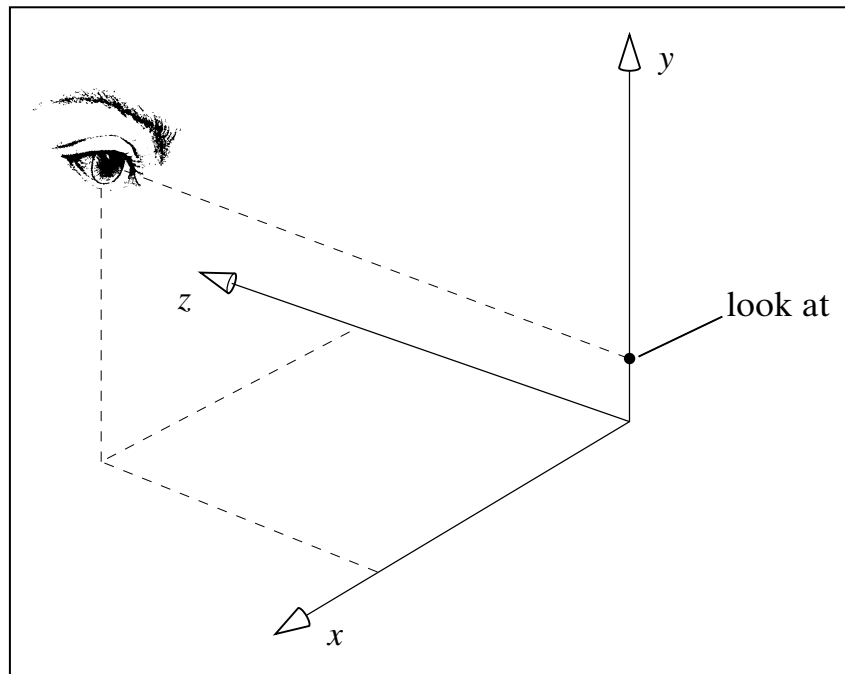
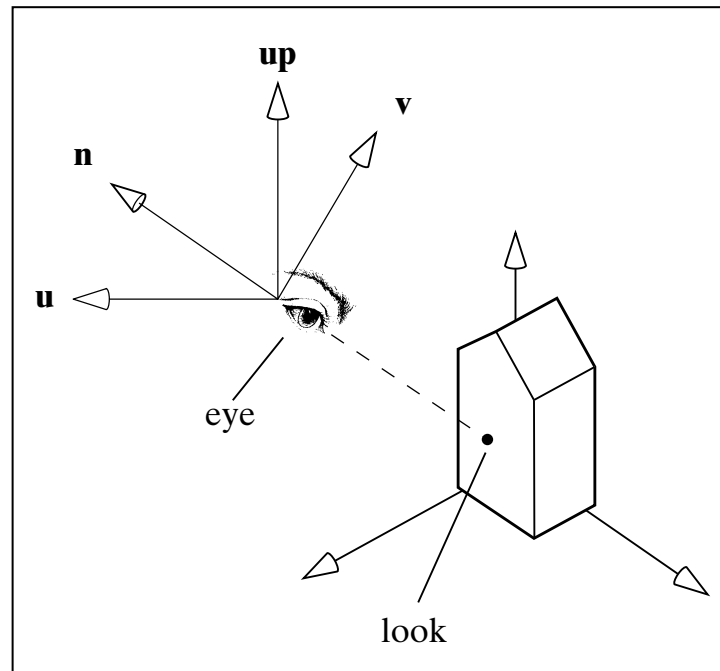


FIGURE 5.57 Converting from world to camera coordinates.



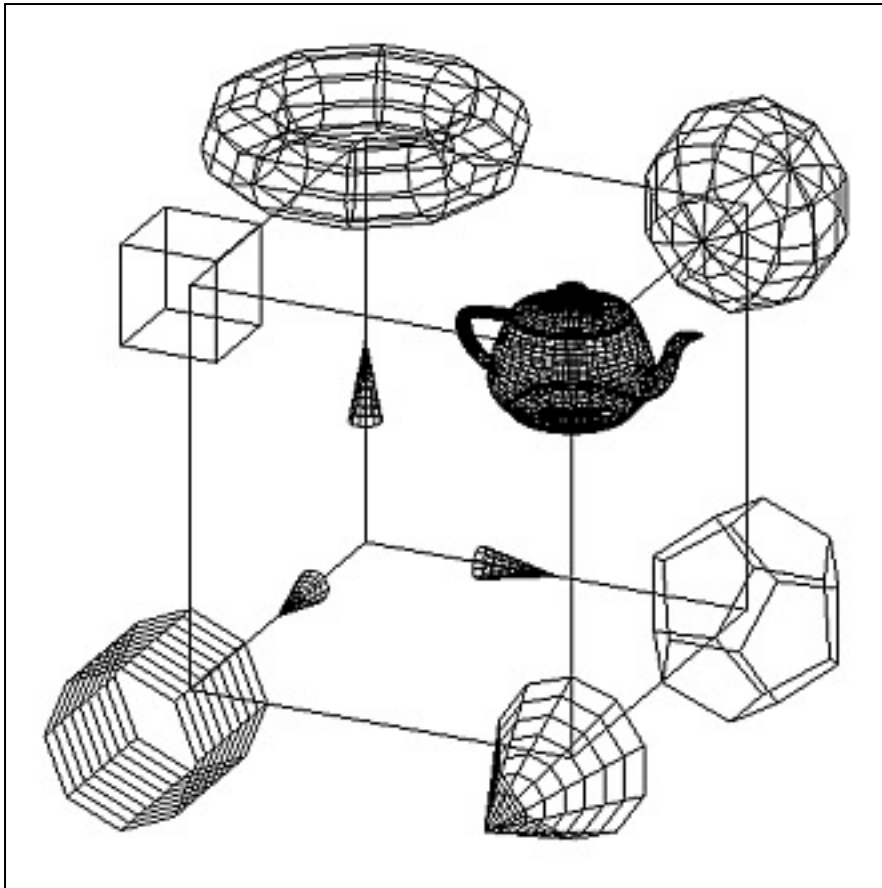
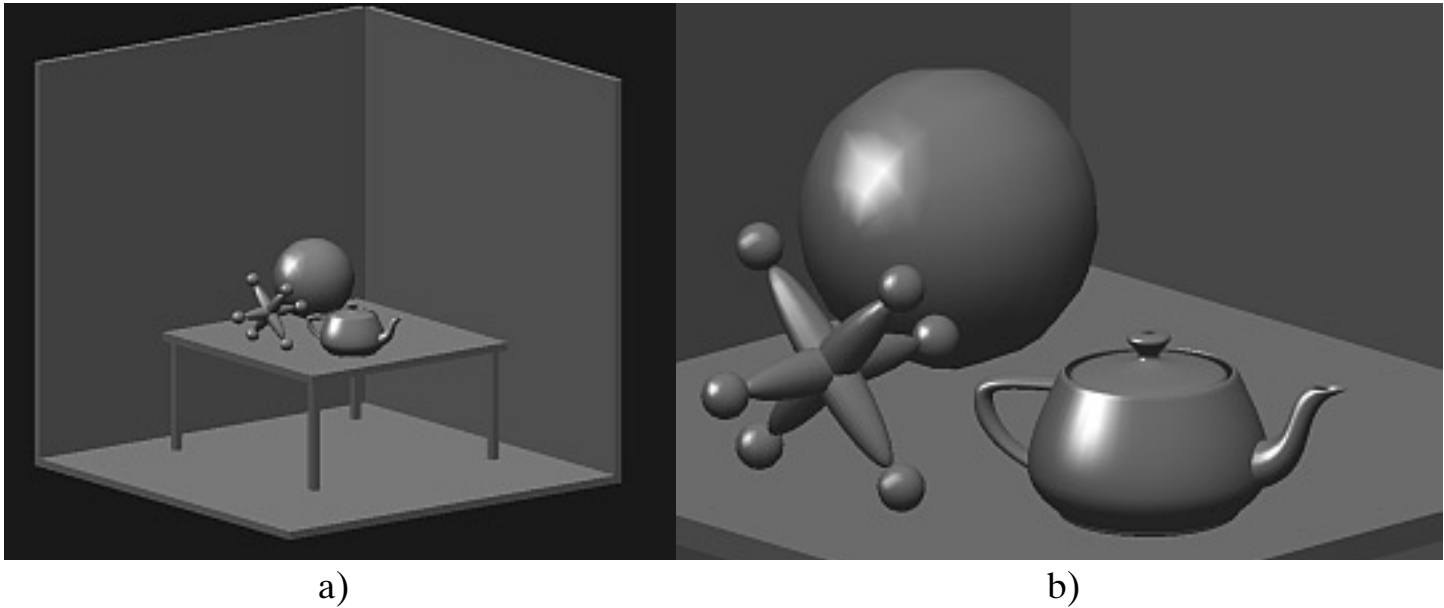


FIGURE 5.59 Wire-frame drawing of various primitive shapes.



a)
b)
FIGURE 5.61 A simple 3D scene
(a) using a large view volume
and (b) using a small view
volume.

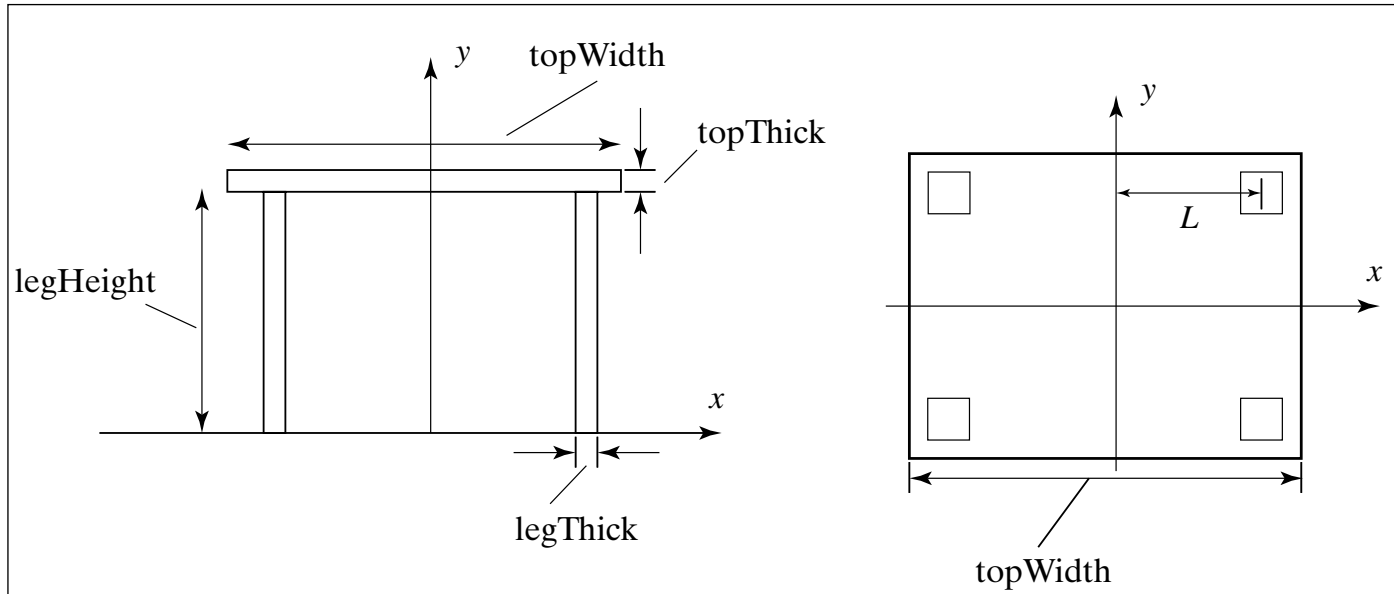


FIGURE 5.62 Designing the table.

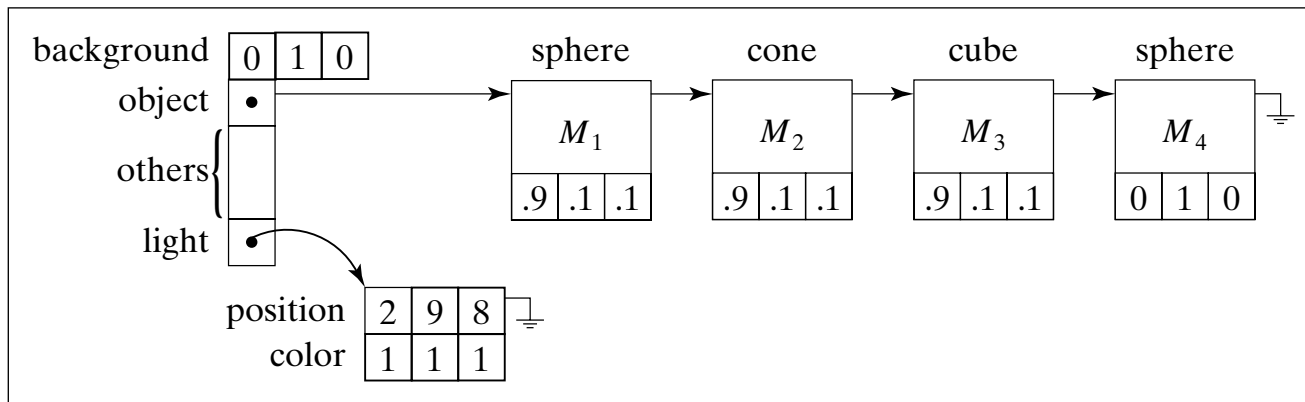


FIGURE 5.64 An object of the Scene class.

```
void Sphere :: drawOpenGL()
{
    tellMaterialsGL(); //pass material data to OpenGL
    glPushMatrix();
    glMultMatrixf(transf.m); // load this object's matrix
    glutSolidSphere(1.0,10,12); // draw a sphere
    glPopMatrix();
}
void Cone :: drawOpenGL()
{
    tellMaterialsGL();//pass material data to OpenGL
    glPushMatrix();
    glMultMatrixf(transf.m); // load this object's matrix
    glutSolidCone(1.0,1.0, 10,12); // draw a cone
    glPopMatrix();
}
```

FIGURE 5.65 The drawOpenGL() methods for two shapes.

FIGURE 5.67 The SDL file to create the scene of Figure 5.61.

```
! - myScenes1.dat
light 20 60 30 .7 .7 .7 !put a light at (20,60,30),color:(.7, .7, .7)
ambient .7 .7 .7 ! set material properties for all of the objects
diffuse .6 .6 .6
specular 1 1 1
specularExponent 50

def jackPart{ push scale .2 .2 1 sphere pop
push translate 0 0 1.2 scale .2 .2 .2 sphere pop
push translate 0 0 -1.2 scale .2 .2 .2 sphere pop
}

def jack{ push use jackPart
rotate 90 0 1 0 use jackPart
rotate 90 1 0 0 use jackPart pop
}

def wall{push translate 1 .01 1 scale 1 .02 1 cube pop}
def leg {push translate 0 .15 0 scale .01 .15 .01 cube pop}

def table{
push translate 0 .3 0 scale .3 .01 .3 cube pop !table top
push
translate .275 0 .275 use leg
translate 0 0 -.55 use leg
translate -.55 0 .55 use leg
translate 0 0 -.55 use leg pop
}
!now add the objects themselves
push translate .4 .4 .6 rotate 45 0 0 1 scale .08 .08 .08 use jack pop
push translate .25 .42 .35 scale .1 .1 .1 sphere pop
push translate .6 .38 .5 rotate 30 0 1 0 scale .08 .08 .08 teapot pop
push translate 0.4 0 0.4 use table pop

use wall
push rotate 90 0 0 1 use wall pop
push rotate -90 1 0 0 use wall pop
```

```

void drawArc2(RealPoint c, double R,
             double startangle, double sweep) // in degrees
{
    #define n 30
    #define RadPerDeg .01745329
    double delang = RadPerDeg * sweep / n;
    double T = tan(delang/2);           // tan. of half angle
    double S = 2 * T/(1 + T * T);      // sine of half angle
    double snR = R * sin(RadPerDeg * startangle);
    double csR = R * cos(RadPerDeg * startangle);
    moveTo(c.x + csR, c.y + snR);
    for(int i = 1; i < n; i++)
    {
        snR += T * csR;           // build next snR, csR pair
        csR -= S * snR;
        snR += T * csR;
        lineTo(c.x + csR, c.y + snR);
    }
}

```

FIGURE 5.68 A fast arc drawer.

FIGURE 5.69 Defining a shear in 3D.

